

# Asset Pricing with Disagreement and Uncertainty about the Length of Business Cycles

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July 11, 2017

## Abstract

We study an economy with incomplete information in which two agents are uncertain and disagree about the length of business cycles. That is, the agents do not question whether the economy is growing or not, but instead continuously estimate how long economic cycles will last—i.e., they learn about the persistence of fundamentals. Learning about persistence generates high and persistent stock return volatility mostly during recessions, but also (to a smaller extent) during economic booms. Disagreement among agents fluctuates and earns a risk premium. A clear risk-return tradeoff appears only when conditioning on the sign and magnitude of disagreement. We confirm these predictions empirically.

**Keywords:** Learning, Uncertainty, Disagreement, Volatility, Risk Premium

**JEL Classification:** D51, D83, G12, G14

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We would like to thank Neng Wang (the editor), an associate editor and two referees for their excellent comments. We also thank Tony Berrada, Mike Chernov, Julien Cujean, Alexander David, Jerome Detemple, Bernard Dumas, Andrea Eisfeldt, Barney Hartman-Glaser, Burton Hollifield, Julien Hugonnier, Arvind Krishnamurthy, Lars-Alexander Kuehn, Ali Lazrak, Francis Longstaff, Hanno Lustig, Chayawat Ornthanalai, Emilio Osambela, Monika Piazzesi, Rodolfo Prieto, Alberto Rossi, Nick Roussanov, Martin Schneider, Ken Singleton, Pascal St.-Amour, Wei Xiong, and Hongjun Yan for their useful advice. We would also like to acknowledge comments from conference and seminar participants at the SFI meeting in Gerzensee, 4th International Forum on Long-Term Risks, UCLA Anderson, 2014 Mathematical Finance Days, 2014 SFS Finance Cavalcade, 2014 WFC, 2014 SITE Summer Workshop, 2014 EFA meeting, 2014 NFA meeting, CMU Tepper, the New York Fed, 2016 International Conference on Capital Markets, and 2016 SGF Conference. Financial support from the Swiss Finance Institute, NCCR FINRISK of the Swiss National Science Foundation, UCLA, and the University of Toronto is gratefully acknowledged.

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# 1 Introduction

It is a common observation that financial asset prices and returns exhibit a strong business cycle behavior. Risk premia and Sharpe ratios tend to rise during recessions (Ferson and Harvey, 1991; Lustig and Verdelhan, 2012). Asset return volatility is time-varying and predictable (Engle, 1982); it increases during recessions (Schwert, 1989), but also during periods of rapid technological progress (Pastor and Veronesi, 2006). The risk-return tradeoff, which states that greater risk demands greater return, is time-varying and its sign flips over time (Rossi and Timmermann, 2011, 2015). So far, no consensus has been reached as to which model can simultaneously explain all of these empirical regularities. The purpose of this paper is to offer such a model.

We study a pure exchange economy with incomplete information in which two agents are uncertain about the length of the business cycle. That is, agents do not question whether the economy is growing or not—the usual learning exercise studied in the literature—but instead continuously wonder how long economic cycles will last. For example, during the Great Recession of 2007-08 there was no debate about whether there was an economic downturn, rather economists were uncertain and disagreed about when recovery would take place (Reinhart and Rogoff, 2009; Howard, Martin, and Wilson, 2011; Bernanke, 2013). In this paper, we show that *learning about the persistence* of economic growth differs from learning about economic growth itself and helps account for a wide range of empirical observations regarding financial asset prices and returns.

A first testable implication is that learning about persistence generates time-varying uncertainty and persistent stock market volatility. The quantity responsible for this, which we call *structural uncertainty*, is defined as the product of two variables: the uncertainty about growth persistence and the difference between the growth rate and its long-term mean. Intuitively, structural uncertainty is a function of how much uncertainty is perceived by agents and the degree to which the economy is in an expansion or contraction. This implies that the way in which structural uncertainty impacts the price of risk, risk premia, and the volatility of stock returns depends on the growth rate of the economy. When the economy is going through recessions or booms, agents face significant structural uncertainty, which increases stock return volatility. This is more severe during recessions, when bad news worsens the agents' forecasts of future growth and increases the persistence (riskiness) of future shocks. We show that there exists a “hockey-stick”-shaped relationship between volatility and economic growth that rationalizes the high levels of volatility observed particularly during recessions (Schwert, 1989; Patton and Timmermann, 2010; Barinov, 2014), but also the less severe levels of volatility during booms such as the Nasdaq bubble in the late 1990's (Pastor and Veronesi, 2006).



Because agents use different sources of information to estimate the length of business cycles, they exhibit time-varying disagreement about persistence in the economy. Based on this, an additional quantity that affects asset prices, which we call *structural disagreement*, is defined as the product of two quantities: the degree to which agents' estimates of the mean-reversion speed of the fundamental diverge from each other and the difference between the fundamental and its long-term mean. Since structural disagreement is enhanced during booms and recessions, this yields a second testable prediction: structural disagreement generates fluctuations in the agents' consumption shares and thereby impacts the market price of risk in the economy. When the economy goes through booms or recessions, structural disagreement is large and the agent with the least favorable economic outlook perceives the risky asset as a bad hedge against fluctuations in her consumption share. Consequently, she requires a large risk premium for holding the risky asset. Through this mechanism, structural disagreement induces fluctuations in the risk premium in the economy.

Taken together, these two predictions show that the risk-return tradeoff in our economy crucially depends on the magnitude and the sign of structural disagreement (which, according to the above definition, can be both positive and negative). Thus, the third testable prediction of our model is that the risk-return tradeoff becomes apparent only when structural disagreement is taken into account. This can rationalize the inconclusive findings in the literature about the sign and the significance of the relation between risk premium and volatility (Glosten, Jagannathan, and Runkle, 1993; Brandt and Kang, 2004).

We test these predictions with S&P 500 returns and U.S. output growth data, from which we build proxies for volatility, risk premium, structural uncertainty, and structural disagreement. We find that indeed the volatility of stock returns features a hockey-stick pattern, being higher in recessions. We then document a clear relationship between structural disagreement and the risk premium, as predicted by the model. Finally, we explore the risk-return tradeoff and find that it is indeed dependent on the sign of structural disagreement. Overall, these empirical results generally support our theoretical model of learning and disagreement about the persistence of economic growth.

In addition to these results, our paper provides a theoretical foundation for GARCH. The persistence of volatility has been described extensively in the empirical literature, but there is a paucity of theoretical explanations.<sup>1</sup> The explanation that we provide here is based on structural uncertainty, which arises endogenously from learning about growth persistence.<sup>2</sup>

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<sup>1</sup>A few preference-based foundations for volatility clustering are provided by Campbell and Cochrane (1999), Barberis, Huang, and Santos (2001), and McQueen and Vorkink (2004). See also Osambela (2015).

<sup>2</sup>Timmermann (2001) shows that existence of structural breaks in the fundamental process induces volatility clustering. David (1997) and Veronesi (1999) show that, when the fundamental follows a Markov-switching process, learning implies volatility clustering. A commonality between our work and theirs is that agents have imperfect information about the economic model, although our model does not feature structural



Finally, our work rationalizes the empirical findings in [Carlin, Longstaff, and Matoba \(2014\)](#), who analyze how model disagreement in the MBS market affects asset prices. The authors show that there is a risk premium associated with disagreement and that disagreement varies over time. It appears that disagreement rises during periods of large market movements, which is consistent with our idea of structural disagreement. We also show that the type of disagreement that we are studying implies a particular pattern that is supported by the data from analyst forecasts on real U.S. GDP growth. Specifically, because agents agree on the fundamental today and have similar beliefs regarding its long-term value, disagreement in the near future and in the long term is likely low. That is, the term structure of disagreement is hump-shaped.

Our approach departs from the existing asset pricing literature in several ways. First, instead of assuming that agents learn about the unobserved growth rate of the economy, we propose a model whereby agents observe the growth rate but learn about its persistence. As we show in the paper, this type of learning is associated with time-varying uncertainty, which contrasts with learning models with similar structures<sup>3</sup> and is empirically plausible ([Jurado, Ludvigson, and Ng, 2015](#)).<sup>4</sup> Furthermore, learning about persistence endogenously generates higher volatility when the economy goes through booms and recessions, and induces an asymmetric response to news in good versus bad times, features responsible for the hockey-stick pattern in volatility. All endogenous quantities in our economy, including volatility and risk premia, are now substantially driven by the level of economic growth and are higher especially during recessions. This view is different from other models of learning in which uncertainty is higher when agents perceive the economy to be “in-between” a discrete set of growth states.<sup>5</sup>

Second, we depart from the usual modeling approach to study the effect of heterogeneous beliefs on asset prices. Typically, this literature assumes that agents agree to disagree about the unobservable fundamental—the expected dividend growth—(e.g., [Scheinkman and Xiong, 2003](#); [Dumas, Kurshev, and Uppal, 2009](#)).<sup>6</sup> Instead, we assume that the fundamental

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breaks or a finite number of states. See also [Collin-Dufresne, Johannes, and Lochstoer \(2015\)](#), who show that parameter learning generates long-lasting risks when a representative agent has a preference for early resolution of uncertainty.

<sup>3</sup>Uncertainty is constant in most learning models, a common result in the broad literature of learning (see [Detemple, 1986](#); [Gennotte, 1986](#); [Dothan and Feldman, 1986](#); [Brennan and Xia, 2001](#), among many others). This arises because priors are Gaussian and all variables are normally distributed. In this case, the conditional variance of the unobservable variable—the Bayesian uncertainty—follows a deterministic path and converges to a steady state. Stochastic uncertainty arises with non-Gaussian distributions (see, for instance, [Detemple, 1991](#); [David, 1997](#); [Veronesi, 1999](#)).

<sup>4</sup>See also [Bloom \(2009\)](#), [Bloom, Floetotto, Jaimovich, Saporta-Eksten, and Terry \(2014\)](#) and [Bachmann, Elstner, and Sims \(2013\)](#).

<sup>5</sup>[David \(1997\)](#); [Veronesi \(1999, 2000\)](#); [Cagetti, Hansen, Sargent, and Williams \(2002\)](#); [David and Veronesi \(2002\)](#); [David \(2008\)](#).

<sup>6</sup>See also [Harris and Raviv \(1993\)](#), [Detemple and Murthy \(1994\)](#), [Kandel and Pearson \(1995\)](#), [Zapatero](#)



is publicly observed and agreed upon at all times, but agents disagree about the parameters of the model that govern its dynamics. This setup is motivated by recent empirical evidence of model disagreement in MBS markets: [Carlin et al. \(2014\)](#) document substantial disagreement among Wall Street mortgage dealers about prepayment speed forecasts, although all of the dealers in the survey are large financial institutions having access to all publicly available information and only very little private information.<sup>7</sup>

Our paper focuses on Bayesian (rational) learning and abstracts from other frictions or behavioral biases. As such, our paper is complementary to earlier contributions in the literature in which volatility clustering and other stylized facts about business cycles can arise from heterogeneous beliefs coupled with liquidity constraints ([Osambela, 2015](#)), from overconfidence and over-extrapolation ([Alti and Tetlock, 2014](#)), or from extrapolative biases ([Hirshleifer, Li, and Yu, 2015](#)). As we explain in the paper, most of these features can enrich and reinforce our main results.

The rest of the paper proceeds as follows. Section 2 defines our model and the learning processes that the agents use, characterizes the market equilibrium, and shows how uncertainty and disagreement affect asset prices. In Section 3, we calibrate the model, present our main theoretical predictions, and test them empirically. Section 4 discusses further considerations about the role played by disagreement, about the persistence of volatility, and about agents' survival in this economy. Section 5 concludes. The Appendix contains all proofs, checks the accuracy of our numerical approximation, and describes our calibration exercise.

## 2 A Model of Disagreement and Uncertainty

Consider a pure exchange economy defined over a continuous-time horizon  $[0, \infty)$ , in which a single consumption good serves as the numéraire. A single risky asset (the *stock*) pays the aggregate output stream,  $\delta$ , which follows the process

$$d\delta_t = \delta_t f_t dt + \delta_t \sigma_\delta dW_t^\delta \quad (1)$$

$$df_t = \lambda_t(\bar{f} - f_t)dt + \sigma_f(\rho dW_t^\delta + \sqrt{1 - \rho^2} dW_t^f) \quad (2)$$

$$d\lambda_t = \kappa(\bar{\lambda} - \lambda_t)dt + \Phi dW_t^\lambda, \quad (3)$$

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(1998), [Basak \(2000, 2005\)](#), [Berrada \(2006, 2009\)](#), [Buraschi and Jiltsov \(2006\)](#), [Li \(2007\)](#), [David \(2008\)](#), [Yan \(2008\)](#), [Xiong and Yan \(2010\)](#), [Cvitanic and Malamud \(2011\)](#), [Cvitanic, Jouini, Malamud, and Napp \(2011\)](#), [Bhamra and Uppal \(2013\)](#), [Buraschi, Trojani, and Vedolin \(2014\)](#), [Buraschi and Whelan \(2013\)](#), [Ehling, Gallmeyer, Heyerdahl-Larsen, and Illeditsch \(2017\)](#), [Osambela \(2015\)](#), [Baker, Hollifield, and Osambela \(2015\)](#), and [Dumas, Lewis, and Osambela \(2016\)](#).

<sup>7</sup>See also [Patton and Timmermann \(2010\)](#), [Andrade, Crump, Eusepi, and Moench \(2017\)](#).



where  $W^\delta$ ,  $W^f$ , and  $W^\lambda$  are three independent Brownian motions under the objective/true probability measure  $\mathbb{P}$ .

The expected output growth rate  $f$ , which we regard as the *fundamental*, mean-reverts around its long-term mean  $\bar{f}$  at speed  $\lambda$ . The mean-reversion speed  $\lambda$  is assumed to fluctuate, as described in (3). This process drives the length of recessions and expansions and can be affected, for instance, by continuous technological change of the economic environment.<sup>8</sup>

The economy is populated by two agents,  $A$  and  $B$ , who trade with each other and derive utility from consumption. Each agent chooses a consumption-trading policy to maximize her expected lifetime utility

$$U_i = \mathbb{E}^i \left[ \int_0^\infty e^{-\beta t} \frac{c_{it}^{1-\alpha}}{1-\alpha} dt \right], \quad (4)$$

where  $\beta > 0$  is the time discount rate,  $\alpha > 0$  is the relative risk aversion coefficient, and  $c_{it}$  denotes the consumption of agent  $i \in \{A, B\}$  at time  $t$ . The expectation in (4) depends on agent  $i$ 's own perception of the economy. The parameters  $\bar{f}$ ,  $\sigma_\delta$ ,  $\sigma_f$ ,  $\rho$ ,  $\kappa$ ,  $\bar{\lambda}$ , and  $\Phi$  are commonly known.

## 2.1 Learning and difference of beliefs

At all times, both agents observe the output  $\delta$  and the fundamental  $f$ . The fundamental can be interpreted as the average (median) forecast of the output growth rate among a large survey of professional forecasters, observed and agreed upon by both agents.

Agents do not observe the mean-reversion speed  $\lambda$  and are therefore tasked with estimating it. This feature distinguishes our model from previous work: in existing models, it is assumed that agents do not observe the fundamental  $f$  and have heterogeneous beliefs about it (e.g., [Scheinkman and Xiong, 2003](#); [Dumas et al., 2009](#)).<sup>9</sup> Here, both agents publicly observe  $f$  and its evolution with no disagreement, but try to estimate its mean-reversion speed  $\lambda$  in order to predict the length of business cycles. The question that agents are facing is how long booms or recessions will last before the economy moves back to its known long-

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<sup>8</sup>The mean-reversion speed can become negative because it follows an Ornstein-Uhlenbeck process. The calibration provided in Table 1, however, imply that the unconditional probability of a negative  $\lambda_t$  is only 0.08%. This ensures that the fundamental is stationary. The stationarity properties of an Ornstein-Uhlenbeck process with stochastic mean-reversion speed are discussed by [Benth and Khedher \(2016\)](#).

<sup>9</sup>Besides long-run behavior, there are other dimensions of parameter uncertainty analyzed in the literature, such as tail events ([Liu, Pan, and Wang, 2005](#)) or regime changes ([Ju and Miao, 2012](#)). See [Collin-Dufresne et al. \(2015\)](#) for a good survey of the literature. The mean-reversion speed  $\lambda$ , which is the focus of this paper, has spawned serious interest and disagreement among practitioners and academics. It has been at the center of understanding recoveries following economic crises ([Reinhart and Rogoff, 2009](#); [Howard et al., 2011](#); [Bernanke, 2013](#)) and in studying long-term trends in economic growth ([Beeler and Campbell, 2012](#); [Bansal, Kiku, and Yaron, 2012](#); [Summers, 2014](#); [Hamilton, Harris, Hatzius, and West, 2015](#)).



term growth rate  $\bar{f}$ . For instance, the issue during the Great Recession of 2007-08 was not whether we were in recession—it was pretty clear we were—but how long it would last.

We introduce heterogeneity of beliefs by adopting the “difference-of-opinion” approach (Harris and Raviv, 1993; Kandel and Pearson, 1995). More precisely, suppose that each agent receives a different signal about  $\lambda$ :

$$ds_t^A = \phi dW_t^\lambda + \sqrt{1 - \phi^2} dW_t^A \quad (5)$$

$$ds_t^B = \phi dW_t^\lambda + \sqrt{1 - \phi^2} dW_t^B, \quad (6)$$

where  $W^A$  and  $W^B$  are two additional, independent Brownian motions. Agents do not learn from each others’ behavior, i.e., they do not trust the information source of the other agent. The parameter  $\phi$  defines the level of divergence of opinion: if  $\phi = 1$ , agents are in perfect agreement and the setup reduces to a representative agent economy; if  $0 < \phi < 1$ , the two signals are different and the agents will disagree about  $\lambda$ . If  $\phi = 0$ , neither of the signals is informative and therefore agents are again in perfect agreement.<sup>10</sup>

The filtered mean-reversion speed (*filter*)  $\hat{\lambda}$  and its posterior variance (*uncertainty*)  $\gamma$  are such that  $\lambda_t$  is normally distributed with mean  $\hat{\lambda}_t$  and variance  $\gamma_t$ . Based on (1)-(6), Bayesian learning implies:<sup>11</sup>

$$d\zeta_t = \left( f_t - \frac{1}{2}\sigma_\delta^2 \right) dt + \sigma_\delta d\widehat{W}_t^\delta \quad (7)$$

$$df_t = \hat{\lambda}_t^i (\bar{f} - f_t) dt + \sigma_f \rho d\widehat{W}_t^\delta + \sigma_f \sqrt{1 - \rho^2} d\widehat{W}_t^{fi} \quad (8)$$

$$d\hat{\lambda}_t^i = \kappa(\bar{\lambda} - \hat{\lambda}_t^i) dt + \frac{\gamma_t}{\sigma_f \sqrt{1 - \rho^2}} (\bar{f} - f_t) d\widehat{W}_t^{fi} + \phi \Phi d\widehat{W}_t^{si}, \quad (9)$$

where  $\zeta \equiv \log \delta$  and  $\widehat{W}^\delta$ ,  $\widehat{W}^{fi}$ , and  $\widehat{W}^{si}$  are independent Brownian motions under the probability measure of agent  $i \in \{A, B\}$ , as defined in Appendix A.1. Note that if  $0 < \phi < 1$ , agents come up with different estimates of  $\lambda$  because of the last term in (9).

This learning exercise results in particular dynamics of the filter. First, its instantaneous variance is directly driven by the fundamental. This is because agents are provided with

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<sup>10</sup>If we were to consider a true/objective probability measure under which the signals  $s^A$  and  $s^B$  had, in fact, zero correlation with  $\lambda$ , then our setup could also be interpreted as a model of overconfidence (Scheinkman and Xiong, 2003): agents place infinite trust on their own signal (although in reality it is pure noise) and completely distrusts other information. Then, an additional layer of heterogeneity can be added by assuming different parameters  $\phi^A$  and  $\phi^B$  (Alti and Tetlock, 2014). In this case, each agent perceives a distinct uncertainty about the future (typically, the uncertainty of the more over-confident agent will be lower). Although this would provide further insights into the interaction between disagreement and overconfidence, the addition of a state variable would unnecessarily complicate the exposition of our model. We further discuss in Section 4.1 comparative statics with respect to the parameter  $\phi$ .

<sup>11</sup>See Theorem 12.7 in Liptser and Shiryaev (2001) and Appendix A.1 for details.



more accurate information about the mean-reversion speed when  $\bar{f} - f$  is large, as can be seen from (8). Consequently, the filter features stochastic volatility, which is higher when the fundamental is away from its long-term mean.

Second, the filter can exhibit regimes of positive or negative correlation with the fundamental. For example, if today the economy is in good times (i.e.,  $f_t > \bar{f}$ ) and agents observe a positive change in the fundamental, then  $\lambda$  is likely to be small (i.e., the present boom is likely to persist). Following the same intuition, if the economy is in bad times (i.e.,  $f_t < \bar{f}$ ) and agents observe a positive change, then  $\lambda$  is likely to be large (i.e., the present recession is likely to be short). Agents thus form *extrapolative expectations*: they regard unusual good or bad past performance of the economy as indicators of a slow-moving economy, or as the economy’s “new normal.”<sup>12</sup>

Both the above-mentioned properties of the filter—stochastic volatility and asymmetric correlation—are endogenously generated from learning. This distinguishes our model from standard learning-based models analyzed in the literature. For instance, when agents learn about the level of an unobservable fundamental (e.g., Scheinkman and Xiong, 2003; Dumas et al., 2009; Whelan, 2014; Dumas et al., 2016), the filter has constant volatility. This is not the case in our setting: while the unobservable variable  $\lambda$  has constant volatility and moves independently from other state variables, its estimate  $\hat{\lambda}$  features a U-shaped stochastic volatility and an asymmetric correlation with the fundamental. Both these features, which result endogenously from learning, will generate most of our results.

The Bayesian uncertainty  $\gamma$  follows the same dynamics for both agents

$$\frac{d\gamma_t}{dt} = (1 - \phi^2)\Phi^2 - 2\kappa\gamma_t - \frac{(\bar{f} - f_t)^2}{\sigma_f^2(1 - \rho^2)}\gamma_t^2. \quad (10)$$

When  $f_t - \bar{f} \neq 0$ , fluctuations in the fundamental are informative about  $\lambda$ . This effect is brought by the last term in (10), which causes uncertainty to change at every instant and never converge to a constant.<sup>13</sup> Learning about the persistence of the fundamental thus endogenously generates fluctuating uncertainty, which makes it different from learning about the fundamental: in the latter case, uncertainty converges rapidly to a constant steady state

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<sup>12</sup>This extrapolative nature of learning is different from “extrapolation bias,” which refers to the tendency to overweight recent events when making decisions about the future (Hirshleifer et al., 2015). It is also different from “over-extrapolation,” which refers to the tendency to believe that a stochastic process is more persistent than it actually is (Alti and Tetlock, 2014). In our case, both agents apply standard Bayesian rules (Brennan, 1998) and do not overweight recent events or wrongly perceive a more persistent fundamental process.

<sup>13</sup>For sufficiently high deviations of the fundamental, the uncertainty could decrease significantly. However, once the first term on the right hand side of (10) dominates the two other terms, uncertainty is drifting up. The process  $\gamma$  is therefore guaranteed to remain positive.



(e.g., [Dumas et al., 2009](#)).<sup>14</sup>

The observable fundamental provides the link between the probability measures of the two agents,  $\mathbb{P}^A$  and  $\mathbb{P}^B$ :

$$d\widehat{W}_t^{fA} = d\widehat{W}_t^{fB} + \frac{(\widehat{\lambda}_t^B - \widehat{\lambda}_t^A)(\bar{f} - f_t)}{\sigma_f \sqrt{1 - \rho^2}} dt, \quad (11)$$

where  $\widehat{\lambda}^B - \widehat{\lambda}^A$  is the difference in beliefs about persistence. Since each agent perceives the economy under a different probability measure, the  $\mathbb{P}^A$ -expectation of any random variable  $X$  can also be computed under  $\mathbb{P}^B$  by using the following relation

$$\mathbb{E}^A[X] = \mathbb{E}^B[\eta X], \quad (12)$$

where the process  $\eta$  is the change of measure from  $\mathbb{P}^B$  to  $\mathbb{P}^A$ . Defining  $\mathcal{O}_t$  as the observation filtration at time  $t$ , the change of measure  $\eta$  satisfies

$$\eta_t \equiv \left. \frac{d\mathbb{P}^A}{d\mathbb{P}^B} \right|_{\mathcal{O}_t} = e^{-\frac{1}{2} \int_0^t \left( \frac{(\widehat{\lambda}_s^B - \widehat{\lambda}_s^A)(\bar{f} - f_s)}{\sigma_f \sqrt{1 - \rho^2}} \right)^2 ds - \int_0^t \frac{(\widehat{\lambda}_s^B - \widehat{\lambda}_s^A)(\bar{f} - f_s)}{\sigma_f \sqrt{1 - \rho^2}} d\widehat{W}_s^{fB}}, \quad (13)$$

and thus has the following dynamics

$$\frac{d\eta_t}{\eta_t} = - \frac{(\widehat{\lambda}_t^B - \widehat{\lambda}_t^A)(\bar{f} - f_t)}{\sigma_f \sqrt{1 - \rho^2}} d\widehat{W}_t^{fB}. \quad (14)$$

We recover the customary change of measure obtained in the learning/difference-of-beliefs literature (e.g. [Scheinkman and Xiong, 2003](#); [Dumas et al., 2009](#); [Whelan, 2014](#); [Dumas et al., 2016](#)), with an important distinction. In our setup, it is the interaction between the demeaned fundamental and the difference between agents' filtered mean-reversion speeds that drives the Radon-Nikodym derivative  $\eta$ . This interaction is absent in previous models, where  $\eta$  is solely driven by the difference between agents' filtered fundamentals.

Based on all the above considerations, we define two state variables particular to our setup of learning and difference-of-beliefs.

**Definition 1.** *The **structural disagreement** and the **structural uncertainty** in this*

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<sup>14</sup>Endogenously fluctuating uncertainty arises in other situations analyzed in the literature. As shown in [Veronesi \(2000\)](#), when drift of fundamentals shifts between two unobservable states at random times, uncertainty changes over time, being at its maximum when the probability of each of the two states is 0.5. This generates a hump-shaped uncertainty. In [Xia \(2001\)](#), learning is a function of the current state variable and thus uncertainty endogenously fluctuates over time.



economy are defined as

$$\mathcal{D} \equiv (\bar{f} - f)(\hat{\lambda}^B - \hat{\lambda}^A) \quad (15)$$

$$\mathcal{U} \equiv (\bar{f} - f)\gamma. \quad (16)$$

These two state variables isolate the effects of disagreement and learning about the unobservable mean-reversion speed. Intuitively, the structural disagreement  $\mathcal{D}$  only matters when the fundamental is away from its long-term mean; it is only then that agents' views of the economy differ through the change of measure  $\eta$ . Similarly, the structural uncertainty  $\mathcal{U}$  only matters when the fundamental is away from its long-term mean. To gain some intuition on why this is the case, consider a simple Euler discretization of the fundamental process:

$$f_{t+1} = f_t + \lambda_t(\bar{f} - f_t) + \varepsilon_{t+1}. \quad (17)$$

Because  $\lambda_t$  is unobservable, the one-step ahead forecast error is given by

$$f_{t+1} - \mathbb{E}_t[f_{t+1}] = \varepsilon_{t+1} + (\lambda_t - \hat{\lambda}_t)(\bar{f} - f_t), \quad (18)$$

which has two terms: the future random shock and the error arising from parameter uncertainty. The magnitude of this latter term grows with the distance between the fundamental and its long-term mean. In other words, uncertainty about the speed of mean-reversion  $\lambda$  matters only when the growth rate of the economy is away from its long-term mean, offering an intuitive justification of our notion of structural uncertainty.

To summarize, several features distinguish our incomplete information setup from previous work. First, the volatility of the filter is stochastic and increases when the fundamental is away from its long-term mean. Second, the sign of the correlation between the filter and the fundamental depends on economic conditions (negative in good times and positive in bad times). Third, uncertainty endogenously fluctuates over time and never converges to a constant. Finally, our model of learning generates two key quantities, structural disagreement and structural uncertainty, that are highly dependent on the state of the economy given by the value of the fundamental. As we describe below, all these features generate novel, testable implications for asset prices.

## 2.2 Equilibrium asset prices

From now on, we choose to work under agent  $B$ 's probability measure  $\mathbb{P}^B$ , which we assume coincides with the true probability measure  $\mathbb{P}$ . That is, agent  $B$  has the correct beliefs. Assuming that markets are complete, we follow [Cox and Huang \(1989\)](#) and solve for the



equilibrium using the martingale approach.<sup>15</sup> The state-price density perceived by agent  $B$ ,  $\xi^B$ , satisfies

$$\xi_t^B = e^{-\beta t} \delta_t^{-\alpha} \left[ \left( \frac{\eta_t}{\Lambda_A} \right)^{1/\alpha} + \left( \frac{1}{\Lambda_B} \right)^{1/\alpha} \right]^\alpha \quad (19)$$

$$= \frac{1}{\Lambda_B} e^{-\beta t} \delta_t^{-\alpha} \omega_{Bt}^{-\alpha}, \quad (20)$$

where  $\Lambda_A$  and  $\Lambda_B$  are the Lagrange multipliers associated with the static budget constraints of agents  $A$  and  $B$ , and  $\omega_{it} \equiv c_{it}/\delta_t$  is the consumption share of agent  $i \in \{A, B\}$  at time  $t$ .<sup>16</sup> The consumption shares are functions of the change of measure  $\eta_t$  and their sum equals one.

According to (20), agent  $B$ 's state-price density depends on the aggregate output  $\delta$  but also on her consumption share  $\omega_{Bt}$ . That is, the agent cares not only about the aggregate level of output (which would be the case in a representative agent economy), but also on how much of the aggregate output she shares with agent  $A$ .

**Proposition 1.** *The risk-free rate and the market price of risk perceived by agent  $B$  are:*

$$r_t = \beta + \alpha f_t - \frac{1}{2} \alpha(\alpha + 1) \sigma_\delta^2 + \frac{1}{2} \frac{\alpha - 1}{\alpha} \frac{\mathcal{D}_t^2}{\sigma_f^2 (1 - \rho^2)} \omega_{At} \omega_{Bt} \quad (21)$$

$$\theta_t^B = \left( \alpha \sigma_\delta \quad \frac{\omega_{At}}{\sigma_f \sqrt{1 - \rho^2}} \mathcal{D}_t \quad 0 \quad 0 \right)^\top. \quad (22)$$

Assuming that the coefficient of relative risk aversion  $\alpha$  is an integer,<sup>17</sup> the equilibrium price-dividend ratio of the risky asset satisfies

$$\frac{S_t}{\delta_t} = \sum_{j=0}^{\alpha} \binom{\alpha}{j} \omega_{At}^j \omega_{Bt}^{\alpha-j} F_j(Z_t), \quad (23)$$

---

<sup>15</sup>Following Dumas et al. (2009) and Dumas et al. (2016), we add to the existing stock and the locally risk-free asset a perpetual bond and two futures contracts whose underlyings are the information signals. That is, futures contracts are used to hedge fluctuations in information signals. Although our entire analysis abstracts from these three additional securities, they are needed to complete markets and therefore allow us to follow the martingale approach.

<sup>16</sup>Derivations are provided in Appendix A.2.

<sup>17</sup>This assumption simplifies the calculus. To the best of our knowledge, it has been first pointed out by Yan (2008) and Dumas et al. (2009). If the coefficient of relative risk aversion is real, the computations can still be performed using Newton's generalized binomial theorem. Bhamra and Uppal (2013) offer a comprehensive analysis for all possible values of the risk aversion.



where

$$F_j(Z_t) \equiv \mathbb{E}_t^B \left[ \int_t^\infty e^{-\beta(u-t)} \left( \frac{\eta_u}{\eta_t} \right)^{\frac{j}{\alpha}} \left( \frac{\delta_u}{\delta_t} \right)^{1-\alpha} du \right]. \quad (24)$$

The 4-dimensional vector of state variables,  $Z$ , is defined by  $Z \equiv [f, \hat{\lambda}^A, \hat{\lambda}^B, \gamma]^\top$ .

**Proof.** See Appendix A.2. □

By inspection of (21) and (22), structural disagreement is a key driver of both the risk-free rate and the market price of risk. The first three components in (21) form the usual risk-free rate in a representative agent economy. First, the risk-free rate increases with the discount factor  $\beta$ . Second, the risk-free rate increases with the fundamental  $f$  (in this case, agents expect higher future consumption and hence lower future marginal utility; future payments due to saving have lower value, which decreases the demand for the risk-free asset and increases the equilibrium risk-free rate). Third, the risk-free rate decreases with the volatility of aggregate output  $\sigma_\delta$  (the higher the volatility, the more agents demand risk-free payments and hence a lower risk-free rate is necessary to clear the market for borrowing and lending).

The last term in (21) comprises an additional effect on the risk-free rate due to disagreement. When the risk aversion coefficient is larger than one, both agents in this economy expect a larger consumption share in the future under their own probability measure (see Equation (67) in Appendix A.2), and thus lower future marginal utility. This effect arises because each agent believes that the other agent's model is partially inaccurate. Therefore, in presence of disagreement, both agents decide to save less today, which increases the equilibrium risk-free rate.

The market price of risk perceived by agent  $B$  in (22) potentially loads on four independent sources of risk: aggregate output risk  $\widehat{W}^\delta$ , fundamental risk  $\widehat{W}^{fB}$ , agent  $B$ 's information risk  $\widehat{W}^{sB}$ , and agent  $A$ 's information risk  $\widehat{W}^{sA*}$ . Only aggregate output risk and fundamental risk are priced. First, agent  $B$  requires a positive price for bearing the risk of fluctuations in aggregate output  $\delta$ , as determined by the first element in the vector (*market price of aggregate output risk*). Second, agent  $B$  requires a price for bearing fundamental risk which affects her consumption through the consumption share process (*market price of fundamental risk*). This second term exists because agents disagree about the interpretation of fundamental shocks.

To characterize the market price of fundamental risk, it is first important to interpret the sign of the structural disagreement  $\mathcal{D}_t$ . Whenever  $\mathcal{D}_t > 0$ , agent  $B$ 's model has a *more favorable* economic outlook. This arises when (i) the economy is going through good times



( $\bar{f} - f_t < 0$ ) and agent  $B$  believes the fundamental to be more persistent than agent  $A$  (a longer economic boom), or (ii) when the economy is going through bad times and agent  $B$  believes the fundamental to be less persistent than agent  $A$  (a shorter recession).

Given this interpretation, when agent  $B$  has a more favorable outlook ( $\mathcal{D}_t > 0$ ), positive shocks to the fundamental increase her consumption share. This induces a positive correlation between her consumption share and the fundamental, and thus agent  $B$  requires a positive premium to bear fundamental risk. Alternatively, when  $\mathcal{D}_t < 0$ , agent  $B$ 's model has a less favorable outlook and her consumption share is negatively correlated with fundamental risk. She is then willing to pay a price to bear fundamental risk. Lastly, if  $\mathcal{D}_t = 0$ , agents have the same forecasts, consumption shares do not fluctuate, and thus there is no market price of fundamental risk. Note also that agent  $B$  requires a larger market price of risk (in absolute value) when the proportion of agent  $A$  in the economy,  $\omega_A$ , is large.

## 2.3 Stock return volatility and equity risk premium

Proposition 2 below characterizes the equilibrium stock return volatility and risk premium.

**Proposition 2.** *The state variables in this economy are  $f_t$ ,  $\hat{\lambda}_t^A$ ,  $\hat{\lambda}_t^B$ ,  $\gamma_t$ , and  $\mu_t \equiv \log \eta_t$ . The diffusion vector of stock returns,  $\Sigma$ , and the risk premium perceived by agent  $B$ ,  $RP_B$ , satisfy*

$$\Sigma = \begin{pmatrix} \frac{S_f}{S} \sigma_f \sqrt{1 - \rho^2} + \frac{\sigma_\delta + \frac{S_f}{S} \sigma_f \rho}{\sigma_f \sqrt{1 - \rho^2}} \left[ -\frac{S_\mu}{S} \mathcal{D} + \left( \frac{S_{\lambda_A}}{S} + \frac{S_{\lambda_B}}{S} \right) \mathcal{U} \right] \\ \phi \Phi \left( \frac{S_{\lambda_A}}{S} \phi^2 + \frac{S_{\lambda_B}}{S} \right) \\ \frac{S_{\lambda_A}}{S} \phi \Phi \sqrt{1 - \phi^4} \end{pmatrix}^\top \quad (25)$$

$$RP_B \equiv \Sigma \theta^B \quad (26)$$

$$= \alpha \sigma_\delta \left( \sigma_\delta + \frac{S_f}{S} \sigma_f \rho \right) + \frac{S_f}{S} \mathcal{D} \omega_A + \left[ \left( \frac{S_{\lambda_A}}{S} + \frac{S_{\lambda_B}}{S} \right) \mathcal{U} \mathcal{D} - \frac{S_\mu}{S} \mathcal{D}^2 \right] \frac{\omega_A}{\sigma_f^2 (1 - \rho^2)} \quad (27)$$

where  $S_y$  denotes the partial derivative of the stock price with respect to the state variable  $y$ , and  $\mathcal{D}$  and  $\mathcal{U}$  are defined in (15) and (16).

**Proof.** Application of Itô's lemma on the stock price defined in (23). □

Because the economy is driven by four sources of risk, the stock return diffusion  $\Sigma$ , expressed in Equation (25), has four components. The instantaneous volatility of stock returns is then computed as the norm of the diffusion vector,  $\sigma \equiv \|\Sigma\|$ . It is important to notice that the structural disagreement  $\mathcal{D}$  and the structural uncertainty  $\mathcal{U}$  directly impact the stock return volatility. We analyze the impact of these objects in Section 3.2.



The risk premium perceived by agent  $B$  in (27) is computed as the vector product between the market price of risk  $\theta^B$  and the stock return diffusion  $\Sigma$ . Because the market price of risk is driven solely by structural disagreement, it follows that disagreement directly impacts the risk premium in the economy. Furthermore, Equation (27) shows that if we set  $\mathcal{D} = 0$ , then uncertainty has no direct impact on the risk premium. This implies that disagreement is an important channel through which uncertainty impacts the risk premium in our model. We will explore these implications in Section 3.3.

Learning about the length of business cycles connects both uncertainty and disagreement with the observable fundamental  $f$ , as shown in Definition 1. This feature is particular to our model and implies that uncertainty and disagreement have an impact only when the fundamental is away from its long-term mean (i.e., when  $f \neq \bar{f}$ ). As the fundamental is closer to its long-term mean, both structural uncertainty and structural disagreement get close to zero. Conversely, a fundamental far from its long-run mean enhances the effects of uncertainty and disagreement on asset returns. We turn now to a quantitative examination of these effects.

### 3 Theoretical and Empirical Results

We begin by calibrating the parameters observable by the agents to real U.S. output growth data. Then, using those results, we provide numerical analysis to characterize how uncertainty and disagreement affect asset prices. Finally, we develop a set of precise empirical predictions and test them using quarterly S&P 500 data.

#### 3.1 Calibration

Set  $\alpha = 3$ ,  $\beta = 0.03$ , and the ratio of Lagrange multipliers equal to one.<sup>18</sup> We calibrate the model to the following data: (i) the real U.S. GDP growth rate; (ii) the median of analyst forecast of the U.S. GDP growth rate for the current quarter; (iii) the 75th percentile of the 1-quarter-ahead analyst forecasts; and (iv) the 25th percentile of the 1-quarter-ahead analyst forecasts. We calibrate all parameters using Maximum Likelihood estimation. The data is at quarterly frequency, from Q4:1968 to Q2:2016, and obtained from the Federal Reserve Bank of Philadelphia.<sup>19</sup>

The parameter estimates and their statistical significance are summarized in Table 1.<sup>20</sup>

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<sup>18</sup>This choice of risk aversion and the subjective discount rate yields a mean price-dividend ratio of about 17 and a mean stock return volatility of about 16%. Equal Lagrange multipliers ensures that agents are endowed with the same initial share of consumption

<sup>19</sup><https://www.philadelphiafed.org/research-and-data/>

<sup>20</sup>See Appendix A.4 for further details on the estimation method.



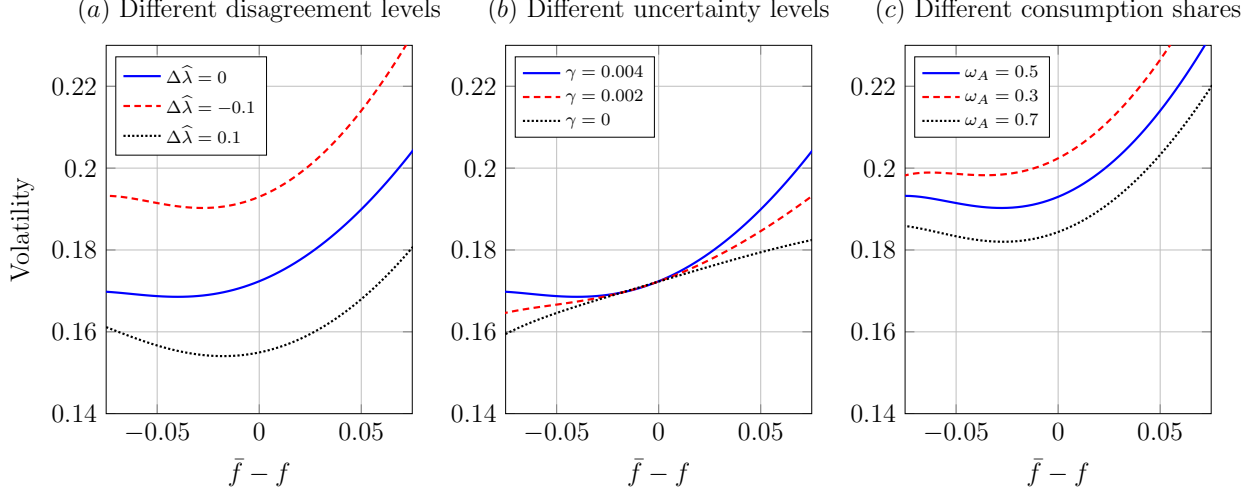
| Parameter                                                | Symbol          | Estimate                               |
|----------------------------------------------------------|-----------------|----------------------------------------|
| Volatility of dividend growth                            | $\sigma_\delta$ | 0.0124***<br>( $8.00 \times 10^{-4}$ ) |
| Long-term fundamental                                    | $\bar{f}$       | 0.0220***<br>( $1.00 \times 10^{-4}$ ) |
| Volatility of fundamental                                | $\sigma_f$      | 0.0233***<br>( $4 \times 10^{-4}$ )    |
| Correlation between dividend and fundamental             | $\rho$          | 0.0694***<br>( $1.95 \times 10^{-2}$ ) |
| Mean-reversion speed of fundamental mean-reversion speed | $\kappa$        | 0.2014***<br>( $2.97 \times 10^{-2}$ ) |
| Long-term fundamental mean-reversion speed               | $\bar{\lambda}$ | 0.2165***<br>( $6.7 \times 10^{-3}$ )  |
| Volatility of fundamental mean-reversion speed           | $\Phi$          | 0.0435***<br>( $5.4 \times 10^{-3}$ )  |
| Difference-of-beliefs parameter                          | $\phi$          | 0.3754***<br>( $4.07 \times 10^{-2}$ ) |

**Table 1: Calibration to the U.S. economy (Maximum Likelihood estimation)**

Parameter values resulting from a Maximum Likelihood estimation, as described in Appendix A.4. Standard errors are in brackets and statistical significance at the 10%, 5%, and 1% levels is respectively labeled \*, \*\*, and \*\*\*.

All parameters are statistically significant at the 99% confidence level. The volatility of dividend growth  $\sigma_\delta$ , the long-term mean of the fundamental  $\bar{f}$ , and the volatility of the fundamental  $\sigma_f$  are consistent with the values used in the asset-pricing literature (e.g., Brennan and Xia, 2001; Bansal and Yaron, 2004; Bansal, Kiku, and Yaron, 2010; Croce, Lettau, and Ludvigson, 2014). The correlation  $\rho$  between the fundamental and the dividend growth rate is positive (analysts adjust their forecasts upward when they observe a positive growth surprise, and downward when they observe a negative growth surprise), but lower than one (analysts use other sources of information to infer the expected growth). The long-term mean-reversion speed of the fundamental implies a half-life of approximately three years, which is slightly shorter than what is assumed in the long-run risk literature. The mean-reversion speed itself is relatively persistent as its half-life is approximately four years. Furthermore, its volatility is significantly different from zero, which lends support to our assumption of time-varying mean-reversion speed.





**Figure 1: Volatility vs.  $(\bar{f} - f)$**

Panel (a) plots the stock return volatility against  $(\bar{f} - f)$  for three different values of disagreement. For this panel, the Bayesian uncertainty  $\gamma$  is fixed at  $\bar{\gamma} = 0.004$  (as defined in Appendix A.1) and  $\omega_A = 0.5$ . Panel (b) plots the stock return volatility against  $(\bar{f} - f)$  for three different values of the uncertainty  $\gamma$ . For this panel, disagreement is fixed at  $\Delta\hat{\lambda} \equiv \hat{\lambda}^B - \hat{\lambda}^A = 0$  and  $\omega_A = 0.5$ . Panel (c) plots the stock return volatility against  $(\bar{f} - f)$  for three different values of agent  $A$ 's consumption share  $\omega_A$ . For this panel, disagreement is fixed at  $\Delta\hat{\lambda} = -0.1$  and  $\gamma = \bar{\gamma} = 0.004$ . Parameter values are provided in Table 1.

### 3.2 Stock return volatility

We turn now to characterizing how uncertainty and disagreement affect stock return volatility using the calibration in Table 1. We solve numerically for equilibrium quantities using the Chebyshev collocation method (details are provided in Appendix A.3). We then compute the stock return volatility by means of Equation (25) of Proposition 2. In Figure 1, we plot the volatility against the deviation between the long-term mean of the fundamental and the fundamental, i.e.  $\bar{f} - f$ . Note that this term appears in the definition of structural uncertainty and structural disagreement, which justifies its choice for the plot. As such, in Figure 1, the right-hand side of zero can be interpreted as “bad times,” whereas the left-hand side can be interpreted as “good times.”

Panel (a) plots the stock return volatility for three different levels of disagreement. Here, we fix  $\hat{\lambda}^A = \bar{\lambda}$ , and assume that  $\hat{\lambda}^B$  takes three different values such that  $\Delta\hat{\lambda} = \hat{\lambda}^B - \hat{\lambda}^A \in \{0, -0.1, 0.1\}$ . Panel (b) plots the stock return volatility for three different levels of uncertainty,  $\gamma \in \{\bar{\gamma}, \bar{\gamma}/2, 0\}$ , where  $\bar{\gamma}$  represents an upper bound which arises from learning (we define and interpret this upper bound in Appendix A.1). Panel (c) plots the stock return volatility for three different values of agent  $A$ 's consumption share,  $\omega_A \in \{0.3, 0.5, 0.7\}$ , with disagreement fixed at  $\Delta\hat{\lambda} = -0.1$ .

All panels of Figure 1 show that stock return volatility significantly varies with the



fundamental. Volatility is U-shaped in  $(\bar{f} - f)$  and reaches a minimum when the fundamental is close to its long-term mean.<sup>21</sup> The feature that generates this U-shaped pattern is the stochastic volatility of the filter, which we describe in Section 2.1. More precisely, when the fundamental is away from its long-term mean, agents accurately update their assessment of  $\lambda$  using fundamental shocks; this amplifies the effect of fundamental shocks, generating higher volatility of the filter and hence higher stock return volatility.

Focusing on panel (a), disagreement has an additional impact on the level of volatility, beyond the impact of the fundamental. Keeping  $\hat{\lambda}^A$  fixed at  $\bar{\lambda}$ , volatility increases when one of the agents—in this particular case agent  $B$ —perceives more persistence in the expected growth rate (dashed line). The three lines in the plot show that this effect is non-negligible: when one agent believes the economy to be more persistent, fundamental shocks have a long-lasting impact on the future growth, thus generating higher stock return volatility.

Turning now to panel (b), most of the intuition can be conveyed by starting with the case when uncertainty is zero (dotted line). In this case, volatility increases almost linearly with  $(\bar{f} - f)$  and is thus higher in bad times (more on this asymmetric effect below). Then, uncertainty amplifies the effect, but only when the fundamental is away from its mean, generating a “hockey-stick” pattern.

The asymmetric effect in panel (b), i.e., higher volatility in bad times, results from the switching sign of the correlation between the filter and the fundamental, which we describe in Section 2.1. More precisely, the filter and the fundamental are positively correlated in bad times and negatively correlated in good times. Shocks in bad times are therefore amplified. For instance, on top of a bad fundamental shock occurring in bad times, agents update and believe the economy is more persistent. Both of these shocks move prices in the same direction and thus magnify the volatility in bad times. In contrast, in good times, when agents update, this moves the filter in the opposite direction as the fundamental, which dampens the volatility of stock returns.

Finally, turning to panel (c), when agent  $B$  perceives more persistence than agent  $A$  (i.e.,  $\Delta\hat{\lambda} < 0$ ), the stock return volatility increases with agent  $B$ ’s consumption share, or equivalently decreases with agent  $A$ ’s. More persistence implies more risk, and this risk is particularly important when the agent perceiving more persistence is the largest consumer in the economy. By the same logic, volatility increases with agent  $A$ ’s consumption share when the disagreement  $\Delta\hat{\lambda}$  is positive. When the disagreement is zero, consumption shares have no impact on volatility.

To summarize, changes in the fundamental have a first-order effect on the volatility of asset returns, which increases in bad times. Adding to this effect, both the uncertainty

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<sup>21</sup>The minimum is not reached at  $f_t = \bar{f}$ , because the stock return variance is a quadratic function of  $(\bar{f} - f_t)$ . Denoting this function by  $a(\bar{f} - f_t)^2 + b(\bar{f} - f_t) + c$ , the minimum is reached at  $f_t = \bar{f} + b/(2c)$ .



and the disagreement about the mean-reverting speed amplify fundamental shocks when the economy is away from its long-term mean. These interactions generate an asymmetric U-shaped (hockey-stick) volatility pattern. As we will show in Section 3.4, these interactions also suggest an approach to empirically test our novel theoretical predictions.

### 3.3 Equity risk premium

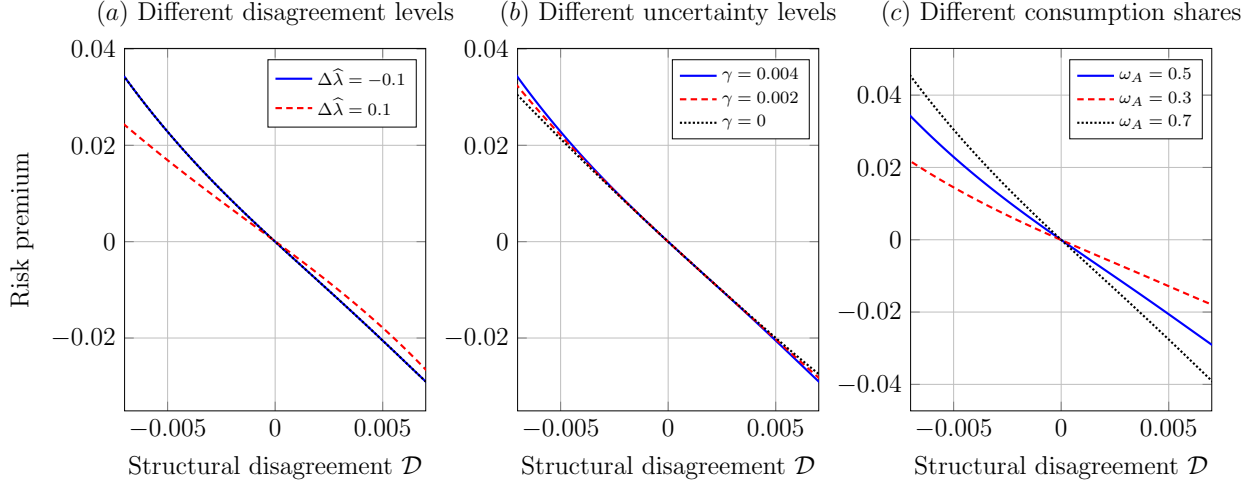
According to our discussion of the market price of fundamental risk in Section 2.2,  $\mathcal{D} > 0$  implies that agent  $B$  has a more favorable economic outlook. With this interpretation in mind, we plot the equity risk premium perceived by agent  $B$  (Equation (27) of Proposition 2) as a function of the structural disagreement  $\mathcal{D}$  in the three panels of Figure 2.

Panel (a) depicts this relationship for two different levels of disagreement. Here, we assume that  $\hat{\lambda}^A = \bar{\lambda}$ , we fix  $\hat{\lambda}^B$  at two different values such that  $\Delta\hat{\lambda} \equiv \hat{\lambda}^B - \hat{\lambda}^A \in \{-0.1, 0.1\}$ , and then vary the level of the fundamental in order to obtain different values of structural disagreement  $\mathcal{D}$ . Panel (a) shows that the risk premium required by agent  $B$  for holding the risky asset is high when her model forecasts a less favorable economic outlook, i.e., when  $\mathcal{D} < 0$  (notice that this result is independent on the sign of  $\Delta\hat{\lambda}$ ). When  $\mathcal{D} < 0$ , the stock is a bad hedge against fundamental risk—fluctuations in the stock price are positively related to fluctuations in agent  $B$ 's consumption share—and thus agent  $B$  requires a large risk premium to hold the risky asset. Conversely, when agent's  $B$  economic outlook is more favorable ( $\mathcal{D} > 0$ ), fluctuations in the stock price are negatively related to fluctuations in her consumption share, which makes the stock a good hedge against fundamental risk and therefore she is willing to pay a premium to hold the risky asset.

Panel (b) of Figure 2 plots the risk premium for three different levels of uncertainty,  $\gamma \in \{\bar{\gamma}, \bar{\gamma}/2, 0\}$ , with disagreement now fixed at  $\Delta\hat{\lambda} = -0.1$ . As Proposition 1 suggests, structural uncertainty affects the risk premium only when disagreement is present. Nonetheless, the plot shows that this effect is quantitatively weak, at least with our calibration.

Panel (c) of Figure 2 plots the risk premium for three different values of agent  $A$ 's consumption share,  $\omega_A \in \{0.3, 0.5, 0.7\}$ , with disagreement again fixed at  $\Delta\hat{\lambda} = -0.1$ , as in Figure 1. When agent  $B$  forecasts a bad economic outlook (i.e.,  $\mathcal{D} < 0$ ), the risk premium she requires to hold the stock is high. This effect is particularly strong when agent  $A$  dominates the economy (when  $A$ 's consumption share is large). Symmetrically, the risk premium required by agent  $B$  is particularly low when she forecasts a good economic outlook, and she is the smallest consumer in the economy.





**Figure 2: Risk premium vs. structural disagreement  $\mathcal{D}$**

Panel (a) plots the equity risk premium perceived by agent  $B$  against the structural disagreement  $\mathcal{D} = (\bar{f} - f)\Delta\hat{\lambda}$  for two different values of disagreement. For this panel, the Bayesian uncertainty  $\gamma$  is fixed at  $\bar{\gamma} = 0.004$  (as defined in Appendix A.1) and  $\omega_A = 0.5$ . We then vary the fundamental  $f$  by keeping  $\Delta\hat{\lambda}$  constant in order to obtain different levels of structural disagreement. Panel (b) plots the equity risk premium for three different values of the Bayesian uncertainty  $\gamma$ . For this panel, disagreement is fixed at  $\Delta\hat{\lambda} = -0.1$  (i.e., agent  $B$  believes the fundamental is more persistent) and  $\omega_A = 0.5$ . Panel (c) plots the equity risk premium for three different values of agent  $A$ 's consumption share  $\omega_A$ . For this panel, disagreement is fixed at  $\Delta\hat{\lambda} = -0.1$  and  $\gamma = \bar{\gamma} = 0.004$ . Parameter values are provided in Table 1.

### 3.4 Empirical Tests

We test our theoretical predictions on the following dataset. We use quarterly S&P 500 excess returns from Q4:1968 to Q2:2016<sup>22</sup> to construct empirical proxies for the risk premium (which we denote by  $RP^e$ ) and for the volatility (which we denote by  $Vol^e$ ). For the risk premium, we model excess returns as an  $AR(p)$  process, where  $p$  is the number of lags. We set the number of lags to  $p = 1$  (only the first lagged return of the estimated  $AR(p)$  features a significant loading). The risk premium is then defined as the fitted value of the estimated  $AR(1)$  process.<sup>23</sup> We then assume that the residuals of the  $AR(1)$  process follow a  $GARCH(1,1)$  model, which yields the stock return volatility.<sup>24</sup> The empirical proxies for structural uncertainty and structural disagreement are defined as  $\mathcal{U}^e \equiv (\bar{f} - f^e)\gamma^e$  and  $\mathcal{D}^e \equiv (\bar{f} - f^e)\Delta\hat{\lambda}^e$ , respectively. The empirical proxies for the fundamental  $f^e$ , the

<sup>22</sup><http://www.econ.yale.edu/shiller/data.htm>

<sup>23</sup>Assuming an  $ARMA(p,q)$  instead of an  $AR(p)$  does not change our results. Moreover, adding the dividend yield as a predictor of future returns (Xia, 2001; Cochrane, 2008; Van Binsbergen and Koijen, 2010) does not affect our results either.

<sup>24</sup>The results hold if we use either a  $GARCH$  model with additional lags or an asymmetric  $GARCH$  model to proxy for stock return volatility.



disagreement  $\Delta\hat{\lambda}^e \equiv \hat{\lambda}^{B,e} - \hat{\lambda}^{A,e}$ , the Bayesian uncertainty  $\gamma^e$ , the mean-reversion speed  $\hat{\lambda}^{B,e}$ , and the consumption share  $\omega_A^e$  are obtained from the Maximum Likelihood estimation performed in Section 3.1. Specifically, with the calibration of Table 1 and the four time series used in the estimation, we build historical model-implied time series of the four Brownian motions governing the economy (more details in Appendix A.4). With these time series at hand, we construct empirical proxies for  $f^e$ ,  $\Delta\hat{\lambda}^e$ ,  $\gamma^e$ ,  $\hat{\lambda}^{B,e}$ , and  $\omega_A^e$ .<sup>25</sup>

**Testable prediction 1** The first testable prediction concerns the shape of the term structure of disagreement. Define disagreement at horizon  $\tau$  as the absolute difference between the agents' expectations of the fundamental at the  $\tau$ -year horizon:

$$D(\tau) \equiv |\mathbb{E}^A(f_\tau) - \mathbb{E}^B(f_\tau)|, \quad (28)$$

where  $\mathbb{E}^A(\cdot)$  and  $\mathbb{E}^B(\cdot)$  are expectations taken under the probability measures of agents  $A$  and  $B$ . We compare this term structure of disagreement with its empirical counterpart,  $D^e(\tau)$ , which we define as the median difference between the 75- and 25-percentile of the  $\tau$ -year-ahead analyst forecast on real U.S. GDP growth (computed over the number of observations), with  $\tau$  varying from the current quarter to 1-year ahead.

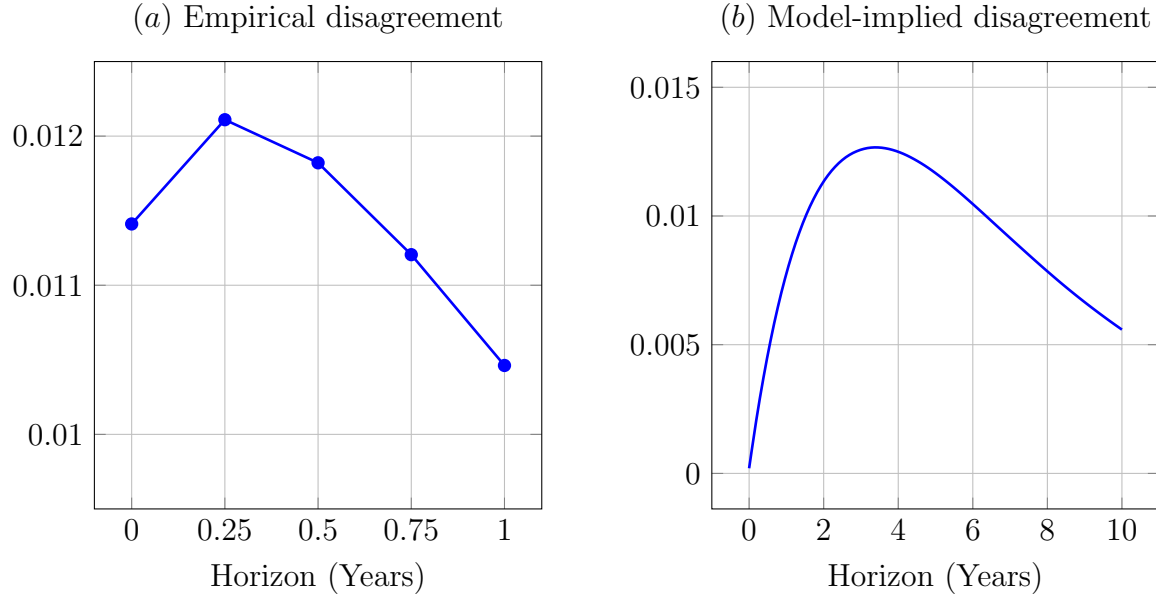
We plot the empirical and model-implied term structures of disagreement in Figure 3. The empirical term structure of disagreement is slightly hump-shaped (left panel), being higher at the 1-quarter horizon and decreasing thereafter. The literature presents mixed conclusions about the shape of the term structure of disagreement: Patton and Timmermann (2010) provide evidence of an increasing term structure of disagreement, whereas Andrade et al. (2017) argue for a decreasing term structure. Our analysis suggests a non-monotonic pattern, which can be either increasing or decreasing depending on the time horizon considered.

Turning to the model-implied term structure of disagreement (right panel), we also obtain a hump-shaped pattern. This pattern is implied by our learning exercise: agents agree on the value of the fundamental today, but disagree over its future path, which generates the hump-shape. Disagreement starts by increasing but then decreases back to zero as the maturity increases (the expectation of the future value of a mean-reverting process tends to its long-term mean as the maturity increases). In contrast, models of dispersion of beliefs where agents disagree about the level of the fundamental (e.g. Dumas et al., 2009) can only generate a monotonically decreasing term structure of disagreement. The left panel shows that the hump-shaped pattern is supported by the data. It validates our motivation to study disagreement about the persistence of the fundamental and not necessarily about its level (with the caveat that the model does not exactly replicate the observed timing of

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<sup>25</sup>We plot the time series of  $f^e$ ,  $\Delta\hat{\lambda}^e$ ,  $\gamma^e$ ,  $\hat{\lambda}^{B,e}$ , and  $\omega_A^e$  in Appendix A.5.





**Figure 3: Empirical and model-implied term structures of disagreement**

Panel (a) plots the empirical term structure of disagreement: disagreement at horizon  $\tau$ ,  $D^e(\tau)$ , is measured as the median of the difference between the 75<sup>th</sup> and 25<sup>th</sup> percentile of the  $\tau$ -year-ahead analyst forecasts on real U.S. GDP growth (obtained from the Federal Reserve Bank of Philadelphia). Panel (b) plots the model-implied term structure of disagreement: disagreement at horizon  $\tau$ ,  $D(\tau)$ , is measured as the absolute difference between the two agents' expectations of the fundamental at the  $\tau$ -year horizon. Parameter values are provided in Table 1. Initial values are  $f_0 = 6\%$ ,  $\hat{\lambda}_0^A = \bar{\lambda} + 2\Phi/\sqrt{2\kappa}$ ,  $\hat{\lambda}_0^B = \bar{\lambda} - 2\Phi/\sqrt{2\kappa}$ ,  $\delta_0 = \eta_0 = 1$ , and  $\gamma_0 = \bar{\gamma}$ , with  $\bar{\gamma}$  defined in Appendix A.1.

disagreement, which peaks at the 1-quarter horizon in the data and at the 3-year horizon in our model; the timing of the peak is determined by the long-term mean  $\bar{\lambda}$  of the two filters  $\hat{\lambda}^A$  and  $\hat{\lambda}^B$ —a larger long-term mean means a higher average mean-reversion speed and thus a peak arising at a shorter horizon).

**Testable prediction 2** The second testable prediction is that stock return volatility is persistent, and its persistence is principally generated by persistence in structural uncertainty. Column (a) of Table 2 confirms that volatility is persistent in the model, by regressing current volatility on past volatility. Moreover, adding the state variables into the regression decreases the loading on past volatility, as shown in column (b). That is, persistence in the state variables induces persistence in volatility. In particular, the strong statistical significance of the loadings on structural uncertainty  $\mathcal{U}$  and  $\mathcal{U}^2$  suggests that the persistence in volatility is principally driven by the persistence in structural uncertainty. Column (c) shows that stock return volatility is also persistent in the data (Engle, 1982; Bollerslev, 1986), although to a lesser extent than in the model. Lending support to the prediction that



|                     | (a)<br>$Vol_t^m$    | (b)<br>$Vol_t^m$                    | (c)<br>$Vol_t^e$    | (d)<br>$Vol_t^e$                  |
|---------------------|---------------------|-------------------------------------|---------------------|-----------------------------------|
| Const.              | 0.012***<br>(0.004) | 0.131***<br>(0.020)                 | 0.046***<br>(0.007) | 0.059<br>(0.055)                  |
| $\mathcal{U}_t$     |                     | 23.04***<br>(3.503)                 |                     | 118.2***<br>(31.85)               |
| $(\mathcal{U}_t)^2$ |                     | 220384***<br>( $2.41 \times 10^4$ ) |                     | 508608*<br>( $2.83 \times 10^5$ ) |
| $\mathcal{D}_t$     |                     | -0.247<br>(0.350)                   |                     | 6.050***<br>(2.007)               |
| $\hat{\lambda}_t^B$ |                     | -0.119***<br>(0.012)                |                     | -0.008<br>(0.056)                 |
| $\omega_{A,t}$      |                     | -0.015<br>(0.034)                   |                     | -0.007<br>(0.112)                 |
| $Vol_{t-1}$         | 0.934***<br>(0.025) | 0.425***<br>(0.037)                 | 0.704***<br>(0.040) | 0.628***<br>(0.042)               |
| $R^2$               | 0.873               | 0.942                               | 0.494               | 0.605                             |
| # Obs.              | 216                 | 216                                 | 190                 | 190                               |

**Table 2: Persistence in stock return volatility vs. persistence in structural uncertainty**

$Vol^m$  and  $Vol^e$  stand for the model-simulated volatility and empirical volatility, respectively. The variables  $\mathcal{U}$ ,  $\mathcal{D}$ ,  $\hat{\lambda}^B$ ,  $\omega^A$ , and  $Vol$  are simulated from the model in columns (a) and (b), and correspond to the empirical proxies in columns (c) and (d). The data are at a quarterly frequency. Newey and West (1987) standard errors are in brackets and statistical significance at the 10%, 5%, and 1% levels is respectively labeled \*, \*\*, and \*\*\*.

persistence in structural uncertainty generates persistence in volatility, column (d) shows that adding the state variables into the regression decreases the loading on  $Vol_{t-1}$  and yields a particularly significant loading on structural uncertainty.

**Testable prediction 3** The third testable prediction concerns the relation between volatility and the risk premium (i.e., the risk-return tradeoff). Our model predicts that this relation depends on the sign of disagreement. More precisely, the risk premium given in Equations (26) and (27) of Proposition 2 can be further written:

$$RP_B = a_0 + a_1 \times f(\mathcal{U}, \mathcal{D})\mathcal{D}, \quad (29)$$

where  $f(\mathcal{U}, \mathcal{D}) \approx \sigma$  is a function directly related to the volatility of stock returns, and  $a_0$  and  $a_1$  are two coefficients that do not depend on  $\mathcal{U}$  and  $\mathcal{D}$ . Equation (29) suggests a linear relationship between the risk premium and the *volatility interacted with structural disagreement*. This relationship holds because most of the variation in volatility is generated



by the second diffusion component in (25), and only the second component of the market price of risk in (22) fluctuates through the structural disagreement  $\mathcal{D}$ . Because structural disagreement can be either positive or negative, the risk-return tradeoff becomes ambiguous. Yet, panel (a) of Figure 4 shows that in our model the risk premium is clearly higher when the product between structural disagreement and volatility is large and negative. Notice that the  $R^2$  of the linear regression fit shown in the legend of the plot is equal to 0.999. That is, the interaction between volatility and structural disagreement explains all of the variation in the risk premium; considering additional explanatory variables such as the structural uncertainty  $\mathcal{U}$  or the consumption share  $\omega_A$  into the regression does not improve the fit.

Columns (a) and (b) of Table 3 test this theoretical prediction. The risk-return tradeoff becomes apparent when the volatility is interacted with the structural disagreement. The relationship is negative and strongly significant, even after controlling for the other state variables and for the individual components of the interaction terms. As in the model, structural uncertainty, the mean-reversion speed, and the consumption share have no impact on the risk premium—see the discussion of panel (a) of Figure 4. The data, however, show that the risk premium remains significantly and positively related to structural disagreement, whereas it is not in the model. In panel (d) of Figure 4, we depict the empirical relation between the risk premium and the volatility interacted with structural disagreement. Comparing panel (d) to its model-implied counterpart in panel (a) shows that the model replicates the relation observed in the data.

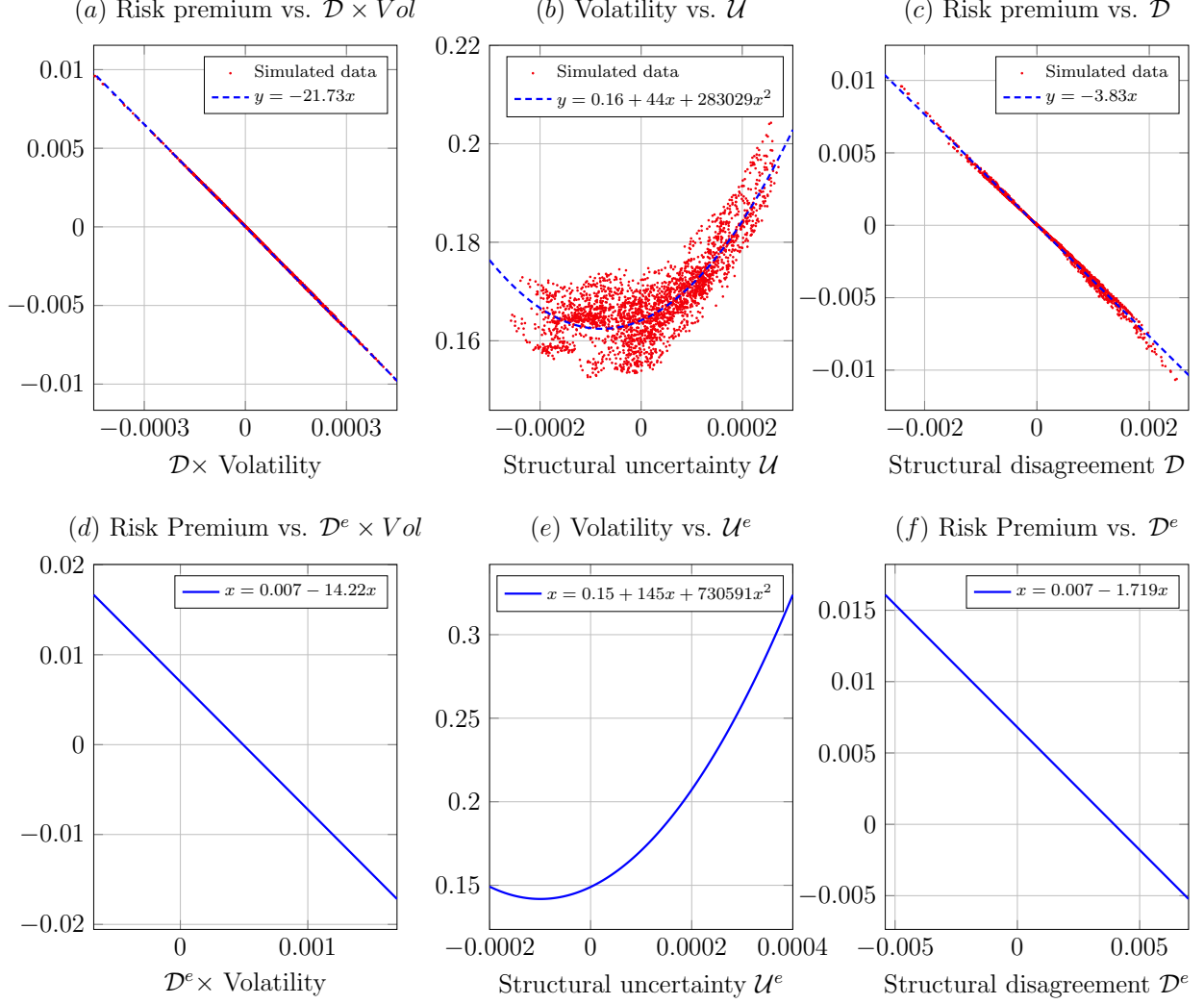
Our model predicts that the risk-return tradeoff is not always positive, and thus can rationalize the inconclusive findings in the literature about the sign and the significance of this relationship.<sup>26</sup> The literature presents evidence that this relationship indeed changes sign. Rossi and Timmermann (2015) show that the risk-return tradeoff is positive (negative) for low (high) volatility levels. Similarly, Ghysels, Plazzi, and Valkanov (2016) find that the ICAPM (Merton, 1973) holds over samples that exclude financial crises. While the relationship (29) does not clearly distinguish between good and bad times in our case, a plausible link with the literature can still be made. When  $\mathcal{D} < 0$ , agent  $B$  has a less favorable outlook about the future, which suggests that current times are comparably better than future times in agent  $B$ 's view. It is during these times that the risk-return tradeoff is positive, as in the above mentioned references.

**Testable prediction 4** The fourth testable prediction is that increased structural uncertainty is associated with a non-linear increase in volatility. We confirm this relationship in panel (b) of Figure 4, where we plot the volatility of stock returns against the structural

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<sup>26</sup>See Backus and Gregory (1993), Glosten et al. (1993), Whitelaw (2000), Brandt and Kang (2004), Rossi and Timmermann (2015), and Adrian, Crump, and Vogt (2015), among many others.





**Figure 4: Theoretical and empirical relationships between risk premium, volatility, structural uncertainty, and structural disagreement**

Panel (a) plots the risk premium against the product  $\mathcal{D} \times Vol$  with model-generated data resulting from one simulation of the economy at weekly frequency over 50 years (2,600 data points). The dashed line represents the linear fit; the equation of the regression line is shown in the legend. Panel (b) plots the stock return volatility against the structural uncertainty  $\mathcal{U}$ . The dashed line represents a quadratic fit; the equation of the regression line is shown in the legend. Panel (c) plots the risk premium against the structural disagreement  $\mathcal{D}$  with the same model-generated data. The dashed line represents the linear fit; the equation of the regression line is shown in the legend. Panel (d) plots the fit resulting from the regression in column (a) of Table 3. Panel (e) plots the fit resulting from the regression in column (c) of Table 3. Panel (f) plots the fit resulting from the regression in column (e) of Table 3. Parameter values are provided in Table 1. Initial values for the simulation are  $f_0 = \bar{f}$ ,  $\hat{\lambda}_0^A = \hat{\lambda}_0^B = \bar{\lambda}$ ,  $\delta_0 = \eta_0 = 1$ , and  $\gamma_0 = \bar{\gamma}$ , where  $\bar{\gamma}$  is defined in Appendix A.1.

uncertainty  $\mathcal{U}$  on model-generated data. We add a quadratic regression line (equation given in the legend of the plot), which confirms the asymmetric hockey-stick pattern. The  $R^2$  of



|                              | (a)<br>$RP^e$         | (b)<br>$RP^e$        | (c)<br>$Vol^e$                    | (d)<br>$Vol^e$                     | (e)<br>$RP^e$         | (f)<br>$RP^e$       |
|------------------------------|-----------------------|----------------------|-----------------------------------|------------------------------------|-----------------------|---------------------|
| Const.                       | 0.0070***<br>(0.0007) | 0.204<br>(0.192)     | 0.148***<br>(0.006)               | 2.963**<br>(1.383)                 | 0.0068***<br>(0.0007) | 0.078<br>(0.179)    |
| $\mathcal{U}^e$              |                       | -391.2<br>(945.4)    | 144.9***<br>(53.4)                | -2131<br>(5220)                    |                       | -1847<br>(1175)     |
| $(\mathcal{U}^e)^2$          |                       |                      | 730591*<br>( $4.33 \times 10^5$ ) | 605385**<br>( $2.38 \times 10^5$ ) |                       |                     |
| $\mathcal{D}^e$              |                       | 4.895**<br>(2.173)   |                                   | 11.540***<br>(3.368)               | -1.719**<br>(0.736)   | -1.253**<br>(0.606) |
| $\hat{\lambda}^{B,e}$        |                       | -0.036<br>(0.024)    |                                   | -0.232<br>(0.143)                  |                       | -0.026<br>(0.023)   |
| $\omega_A^e$                 |                       | 0.052<br>(0.034)     |                                   | -0.078<br>(0.246)                  |                       | 0.053*<br>(0.032)   |
| $\mathcal{D}^e \times Vol^e$ | -14.22***<br>(5.08)   | -39.38***<br>(14.56) |                                   |                                    |                       |                     |
| $\bar{f} - f^e$              |                       | 1.449<br>(3.760)     |                                   | 9.137<br>(20.728)                  |                       | 7.206<br>(4.662)    |
| $\gamma^e$                   |                       | 0.022<br>(0.016)     |                                   | -677.3**<br>(330.7)                |                       | -22.868<br>(44.716) |
| $\Delta \hat{\lambda}^e$     |                       | -0.005<br>(0.024)    |                                   | 0.293**<br>(0.135)                 |                       | 0.003<br>(0.016)    |
| $Vol^e$                      |                       | -53.33<br>(48.86)    |                                   |                                    |                       |                     |
| $R^2$                        | 0.105                 | 0.240                | 0.166                             | 0.308                              | 0.051                 | 0.173               |
| # Obs.                       | 191                   | 191                  | 191                               | 191                                | 191                   | 191                 |

**Table 3: Empirical tests of the relations between S&P 500 risk premium and return volatility vs. structural uncertainty and disagreement**

Columns (a) and (b) test the relation between the risk premium and volatility. Columns (c) and (d) test the relation between volatility and the state variables. Columns (e) and (f) test the relation between the risk premium and the state variables. [Newey and West \(1987\)](#) standard errors are in brackets and statistical significance at the 10%, 5%, and 1% levels is respectively labeled \*, \*\*, and \*\*\*.

the regression is 0.74, which shows that structural uncertainty explains most of the variation in stock return volatility. Adding the structural disagreement  $\mathcal{D}$  and the consumption share  $\omega_A$  as explanatory variables increases the  $R^2$  by one percentage point only, whereas adding the mean-reversion speed  $\hat{\lambda}^B$  increases the  $R^2$  to 0.90. The loading on  $\hat{\lambda}^B$  is negative and significant, which means that less persistence implies less equity risk ([Bansal and Yaron, 2004](#)).

Columns (c) and (d) of Table 3 lend support to this theoretical prediction. The S&P



500 return volatility tends to increase with structural uncertainty; moreover, volatility is a quadratic function of structural uncertainty.<sup>27</sup> This holds even after controlling for the other state variables and for the individual components of the interaction terms. Indeed, the quadratic coefficient in column (d) remains positive and statistically significant. In line with the theory, volatility is not impacted by the consumption share—see the discussion of panel (b) of Figure 4. It is worth mentioning that disagreement is a significant driver of volatility in the data, but less in the model (at least with the current calibration—see Section 4.1 for a discussion). Furthermore, the loading on the mean-reversion speed is negative as in the model, but only weakly significant (its p-value is 0.105). The empirical relation between volatility and structural uncertainty is depicted in panel (e) of Figure 4. The relation features a hockey-stick pattern, as our model predicts in panel (b).

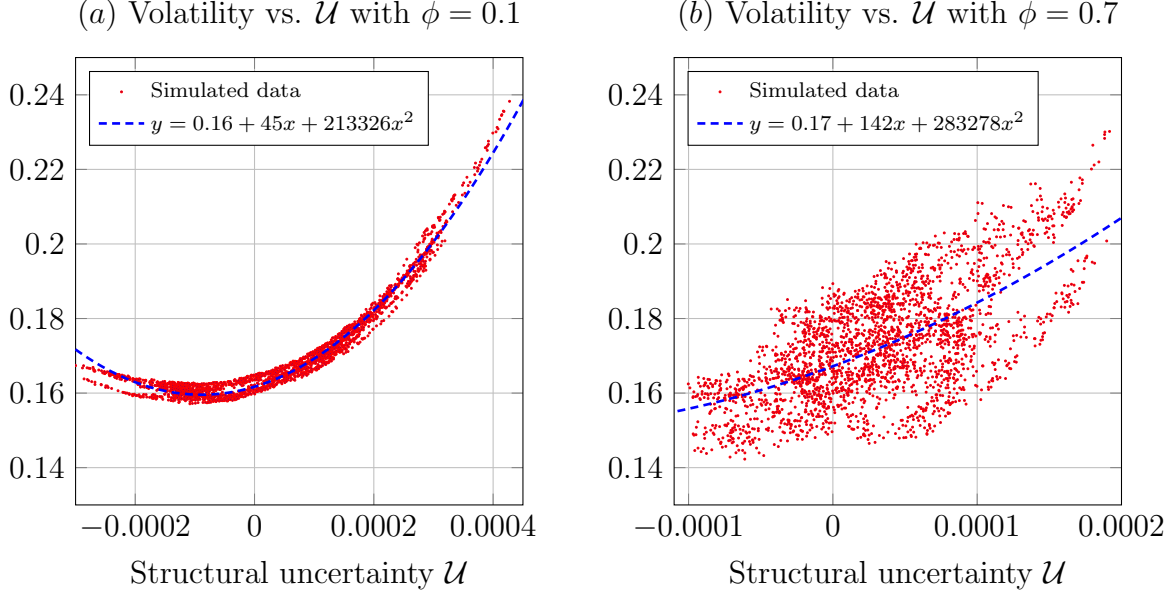
**Testable prediction 5** The fifth and final testable prediction is that the equity risk premium decreases with structural disagreement. Panel (c) of Figure 4 confirms this decreasing relationship, with the equation of the linear regression fit shown in the legend of the plot. The  $R^2$  of the regression is 0.996, which shows that structural disagreement explains all of the variation in the risk premium. As a consequence, adding any other explanatory variables such as the consumption share  $\omega_A$  or the structural uncertainty  $\mathcal{U}$  into the regression does not improve the fit.

Columns (e) and (f) of Table 3 test this theoretical prediction. The negative and significant loading on the structural disagreement is consistent with our model’s prediction that the risk premium decreases with structural disagreement. This negative relation is highly statistically significant, even when the other state variables and the individual components of the interaction terms are considered as controls. It is also worth noting that the consumption share has a weakly significant impact on the risk premium in the data, whereas this impact is nonexistent in the model—see the discussion of panel (c) of Figure 4. The empirical relation between the risk premium and structural disagreement is depicted in panel (f) of Figure 4. Comparing panel (f) with its model-implied counterpart in panel (c) shows that the empirical and model-implied relations are similar.

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<sup>27</sup>Note that a quadratic fit between volatility and the demeaned fundamental ( $Vol_t^e = a_0 + a_1(\bar{f} - f_t^e) + a_2(\bar{f} - f_t^e)^2 + \epsilon_t$ ) yields  $a_1 = 0.575^{***}$ ,  $a_2 = 11.484^*$ , and  $R^2 = 0.16$ , which shows that volatility is also a quadratic function of the fundamental.





**Figure 5: The role of the parameter  $\phi$**

Both panels plot the stock return volatility against the structural uncertainty  $\mathcal{U}$  with model-generated data resulting from one simulation of the economy at weekly frequency over 50 years (2,600 data points). The dashed lines represent quadratic fits, with regression equations shown in the legends. In panel (a) we fix  $\phi = 0.1$ , whereas in panel (b) we fix  $\phi = 0.7$ . Unless otherwise specified, parameter values are provided in Table 1.

## 4 Additional Results and Robustness Checks

### 4.1 More on the role played by disagreement

The parameter  $\phi$  affects how much disagreement is in the market and how much uncertainty agents face. Higher  $\phi$  implies better information and less uncertainty. We analyze now the role played by this parameter in our results.

In Appendix A.2, we show that the dynamics of disagreement are given by:

$$d\Delta\hat{\lambda}_t = - \left( \kappa + \frac{\gamma_t (\bar{f} - f_t)^2}{\sigma_f^2 (1 - \rho^2)} \right) \Delta\hat{\lambda}_t dt + \begin{pmatrix} 0 & 0 & \phi\Phi(1 - \phi^2) & \phi\Phi\sqrt{1 - \phi^4} \end{pmatrix} d\widehat{W}_t, \quad (30)$$

which implies that  $\phi$  affects the instantaneous volatility of disagreement. As previously discussed in Section 2.1, when  $\phi$  is either zero or one, the agents are in perfect agreement. The instantaneous volatility of disagreement is magnified in our model when  $\phi$  takes an intermediate value (i.e., when  $\phi \approx 0.7$ ).

In Figure 5, we consider two different values of  $\phi$  (the calibrated value of Table 1 is  $\phi = 0.3754$ ):  $\phi = 0.1$  and  $\phi = 0.7$ . In the first case, fluctuations in disagreement are relatively small when compared to our benchmark calibration, whereas in the latter case,



the fluctuations are larger. We then simulate the economy as in Section 3.4 and make the same plot as panel (a) of Figure 4. The two plots in Figure 5 show the role played by disagreement. When  $\phi = 0.1$ , structural uncertainty is the sole driver of volatility and fluctuations in disagreement do not add much variability. When  $\phi = 0.7$ , fluctuations in disagreement are more important and explain a larger fraction of the variation in volatility.

## 4.2 Uncertainty and the persistence of volatility

Most of the fluctuations in volatility are generated by fluctuations in structural uncertainty  $\mathcal{U}$  (Section 3.4). This implies that the persistence of stock return volatility is directly related to the persistence of structural uncertainty. Given that structural uncertainty is endogenously generated by the learning of agents, it is a strongly persistent process.<sup>28</sup> Stock return volatility is thus persistent in our model because the structural uncertainty resulting from learning about the mean-reversion speed is persistent. This offers a plausible theoretical foundation of the GARCH behavior commonly observed in financial markets (Engle, 1982; Bollerslev, 1986).

Since the structural uncertainty is the product of the demeaned fundamental  $\bar{f} - f$  and the Bayesian uncertainty  $\gamma$ , it is not clear whether the persistence in return volatility is implied by that in the fundamental or that in the Bayesian uncertainty. One way to show that it is the persistence in Bayesian uncertainty that generates most of the persistence in the stock return volatility is to consider different values for  $\bar{\lambda}$ . In Table 4, we estimate the 1-month autocorrelation of volatility (on model-simulated data) for different values of  $\bar{\lambda}$ . As  $\bar{\lambda}$  increases, the fundamental becomes significantly less autocorrelated (i.e., the fundamental becomes a fast reverting process as opposed to a persistent one) but uncertainty remains strongly persistent, and so does the equilibrium stock return volatility.<sup>29</sup>

In our model, disagreement about the length of the business cycle is the main driver of the equilibrium risk premium. With the benchmark calibration of Table 1, we obtain (from model-simulated data) a 1-month autocorrelation of the risk premium of 0.948, whereas disagreement features a 1-month autocorrelation of 0.992. Given this, disagreement appears

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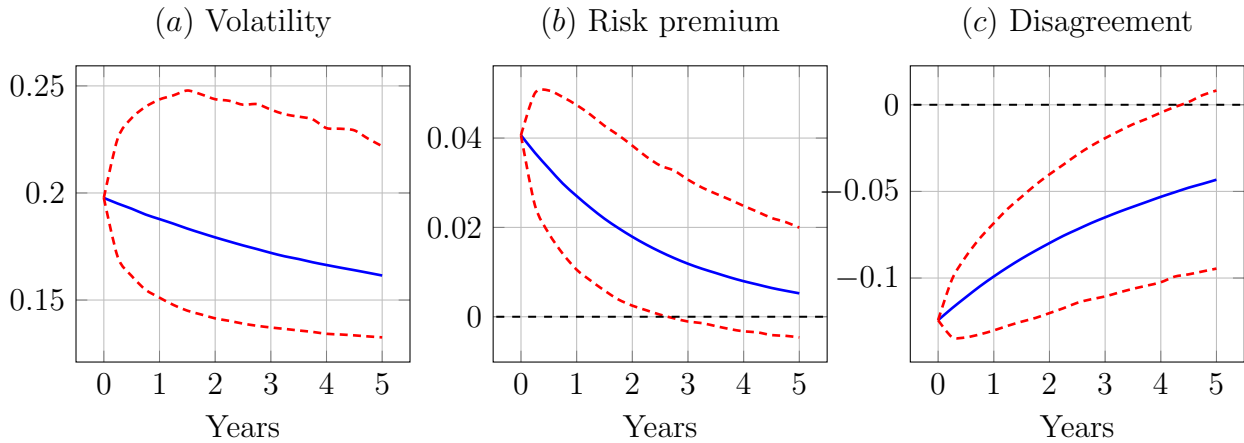
<sup>28</sup>It is straightforward to understand why learning implies persistent uncertainty. If uncertainty is high, agents need not one but a succession of high quality signals for uncertainty to decrease significantly (conversely, a succession of low quality signals are needed for uncertainty to increase significantly). Collin-Dufresne et al. (2015) show that, when investors need to learn about the constant expected consumption growth rate of the economy, uncertainty is strongly persistent and converges to a constant steady state. In their equilibrium model, such persistence implies a large risk premium when investors have Epstein and Zin (1989) preferences with a sufficiently large elasticity of intertemporal substitution. In our model, uncertainty is indeed persistent but never converges to a constant steady state because its dynamics depend on the fundamental, as shown in (10).

<sup>29</sup>In Appendix A.6 we depict one model-simulated path of volatility and the state variables, which provides additional evidence that persistence in the Bayesian uncertainty drives persistence in volatility.



| Parameter values      | Persistence fundamental $f$ | Persistence uncertainty $\gamma$ | Persistence volatility $\sigma$ |
|-----------------------|-----------------------------|----------------------------------|---------------------------------|
| Benchmark calibration | 0.972                       | 0.998                            | 0.987                           |
| $\bar{\lambda} = 1$   | 0.923                       | 0.997                            | 0.986                           |
| $\bar{\lambda} = 2$   | 0.808                       | 0.994                            | 0.982                           |
| $\bar{\lambda} = 5$   | 0.632                       | 0.990                            | 0.981                           |

**Table 4: Persistence in stock return volatility vs. persistence in fundamental**  
This table reports the 1-month autocorrelation in the fundamental  $f$ , Bayesian uncertainty  $\gamma$ , and stock return volatility. Unless stated otherwise, parameter values are provided in Table 1. In rows 2 to 4, the parameter  $\sigma_f$  is chosen such that the long-term volatility of the fundamental,  $\sigma_f/\sqrt{2\bar{\lambda}}$ , is equal to its benchmark counterpart.



**Figure 6: Volatility, risk premium, and disagreement after a recessionary shock**

The solid lines show the average values for volatility (panel *a*), risk premium (panel *b*), and disagreement  $\hat{\lambda}^B - \hat{\lambda}^A$  (panel *c*), averaged across 10,000 simulated 5-year paths at weekly frequency. The dashed lines plot the 5th and 95th percentiles computed across the simulated paths. Parameter values are provided in Table 1. Initial values are  $f_0 = -5\%$ ,  $\hat{\lambda}_0^A = 0.22$ ,  $\hat{\lambda}_0^B = 0.1$ ,  $\delta_0 = \eta_0 = 1$ , and  $\gamma_0 = \bar{\gamma}$ , where  $\bar{\gamma}$  is defined in Appendix A.1.

to drive the persistence of the risk premium in this economy.

We conclude this section with an illustration of the persistent dynamics of the volatility and risk premium after the economy experiences a recessionary shock. Suppose that professional forecasters estimate the growth rate of the economy at  $-5\%$  (approximately two unconditional standard deviations below the long-term growth  $\bar{f} = 2.2\%$ ). Assume further that the two agents consider two different mean-reversion speeds,  $\hat{\lambda}^A = \bar{\lambda} = 0.22$  and  $\hat{\lambda}^B = 0.1$  (agent *B* has a less favorable economic outlook and expects a relatively longer recession).

Figure 6 illustrates the evolution of the volatility, risk premium, and disagreement over five years at weekly frequency. The solid lines represent averages across 10,000 simulations.<sup>30</sup>

<sup>30</sup>The average volatility across simulations and time is 16%, the average risk premium is 0.7%, and the



Panel (a) shows that volatility increases to about 20% (in annualized terms) and then goes down slowly over the next five years (solid line)<sup>31</sup>. The dashed lines are the 5th and 95th percentiles computed across 10,000 simulations. The take-away message of this exercise is that volatility is persistent and features a lot of variability. We have tried several other specifications, including an initial situation without disagreement, and the results are similar. This example illustrates that learning about the mean-reversion speed of the fundamental induces GARCH-like variation in the volatility of stock returns.

Turning to panel (b), the risk premium required by agent  $B$  for holding the asset is large and positive (recall that agent  $B$ 's model has a less favorable economic outlook). One important consideration here is that if we start with an initial situation without disagreement, then the risk premium is close to zero (although it still experiences fluctuations). Disagreement is therefore the main driver of risk premia, whereas uncertainty mostly explains the persistent fluctuations in volatility.

Finally, panel (c) shows the evolution of disagreement (i.e., the difference  $\hat{\lambda}^B - \hat{\lambda}^A$ ) over the five-year period of our simulated sample, averaged across 10,000 simulations. Disagreement takes a long time to converge back to zero. Furthermore, the 5th and 95th percentile lines show that disagreement is very volatile. Note also that, although agent  $B$  believes initially that the fundamental is more persistent than agent  $A$ , there is a chance that in the near future these beliefs will reverse and agent  $B$ 's model features a less persistent fundamental.

### 4.3 Survival

The validity of our theoretical results in the long run depends on whether both agents survive in the economy for a sufficiently long period of time. To investigate this, we follow [Dumas et al. \(2009\)](#) and analyze the distribution of the agents' future consumption shares. Consistent with previous sections, we perform our analysis under the probability measure of agent  $B$  (i.e., we assume that the beliefs of agent  $B$  coincide with the objective—*true*—beliefs).

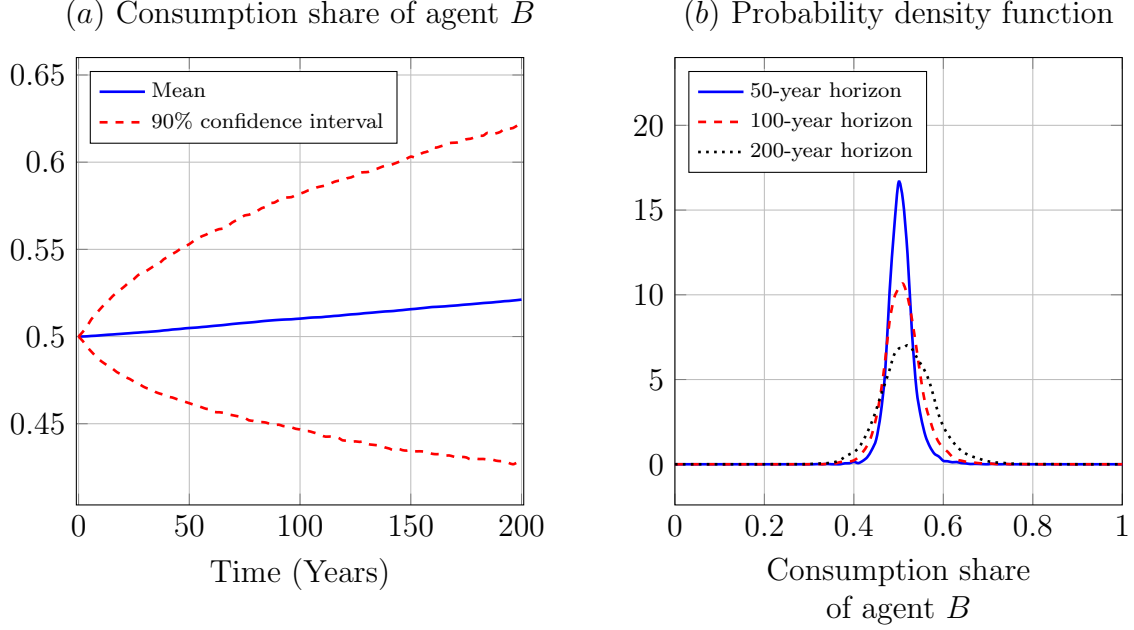
Figure 7 plots the distribution of the consumption share of agent  $B$  resulting from 10,000 simulated economies up to 200 years into the future. Panel (a) plots the average consumption share and its 90% confidence interval, whereas panel (b) plots the probability density function

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average risk-free rate is 8%. The average risk premium and average risk-free rate would better match their empirical counterparts if agents had habit formation, as in [Chan and Kogan \(2002\)](#), [Xiouros and Zapatero \(2010\)](#), [Bhamra and Uppal \(2013\)](#), and [Ehling et al. \(2017\)](#) among others. Other options are recursive preferences ([Epstein and Zin, 1989](#); [Weil, 1989](#)) or dividend leverage ([Abel, 1999](#)). As these extensions would not add any insights to the main predictions of our model, we decide to keep the setup simple and focus on the dynamic properties of asset prices.

<sup>31</sup>Given our parameter values, this level of volatility is substantial: the volatility of the dividend growth is 1.2%, the volatility of the fundamental is 2.2% (see Table 1), and the risk aversion is  $\alpha = 3$ .





**Figure 7: Distribution of the consumption share of agent  $B$**

Panel (a) plots the mean (solid line) and the 90% confidence interval (dashed lines) of the consumption share of agent  $B$ , resulting from 10,000 simulated economies. Panel (b) plots the probability density function of the consumption share of agent  $B$  at a 50-year (solid line), 100-year (dashed line), and 200-year (dotted line) horizon. Parameter values are provided in Table 1. Initial values are  $f_0 = \bar{f}$ ,  $\hat{\lambda}_0^A = \hat{\lambda}_0^B = \bar{\lambda}$ ,  $\delta_0 = \eta_0 = 1$ , and  $\gamma_0 = \bar{\gamma}$ , where  $\bar{\gamma}$  is defined in Appendix A.1.

for three different horizons. The panels show that both agents' consumption shares remain non-trivial for more than 200 years. Indeed, agent  $A$ 's misperceptions of the true data-generating process implies that her consumption share is on average 45% after 200 years. The relatively small average loss in agent  $A$ 's consumption share suggests that agent  $A$ 's misperceptions are relatively mild.<sup>32</sup> Importantly, both plots show that the distributions of the consumption shares are highly concentrated around 0.5, even at the 200-year horizon. Overall, this analysis suggests that the theoretical results presented in the previous sections are likely to hold for significantly long periods of time, as neither of the agents is likely to vanish in the short term.

<sup>32</sup>Kogan, Ross, Wang, and Westerfield (2016) conduct a thorough analysis of the “market selection hypothesis” and develop necessary and sufficient conditions for survival and price impact. They show that agents with less accurate forecasts maintain a nontrivial consumption share and affect prices if the forecast errors accumulate slowly enough over time. Other references are De Long, Summers, Shleifer, and Waldman (1991), Yan (2008), and Kogan, Ross, Wang, and Westerfield (2006).



## 5 Conclusion

In this paper, we show that disagreement and uncertainty about the persistence of fundamentals fits salient features of asset prices and return dynamics. When agents need to update their beliefs about the length of the business cycle, uncertainty fluctuates, leading to new asset pricing implications. We characterize these effects and reach three primary conclusions.

First, this type of learning implies persistent stock return volatility, which provides a theoretical explanation for GARCH-type processes. Second, the growth rate of the economy governs the “structural uncertainty,” which fluctuates and magnifies stock market volatility in recessions and booms, but also the “structural disagreement,” which generates fluctuations in risk premia. Third, the risk-return tradeoff in the economy depends on the value and sign of the structural disagreement. A clear risk-return tradeoff appears when this relationship is properly accounted for.

We test these theoretical predictions with S&P 500 return and U.S. output growth data and find overall support from them. We conclude that these novel implications add to the established literature on learning and heterogeneous beliefs and that they provide plausible explanations for known empirical observations.



# A Appendix

## A.1 Learning

Following the notations of [Liptser and Shiryaev \(2001\)](#), agent  $i$  observes the vector

$$\begin{pmatrix} d\zeta_t \\ df_t \\ ds_t^i \end{pmatrix} = (A_0 + A_1\lambda_t)dt + B_1dW_t^\lambda + B_2 \begin{pmatrix} dW_t^\delta \\ dW_t^f \\ dW_t^i \end{pmatrix} \quad (31)$$

$$= \left[ \begin{pmatrix} f_t - \frac{1}{2}\sigma_\delta^2 \\ 0 \\ 0 \end{pmatrix} + \begin{pmatrix} 0 \\ \bar{f} - f_t \\ 0 \end{pmatrix} \lambda_t \right] dt + \begin{pmatrix} 0 \\ 0 \\ \phi \end{pmatrix} dW_t^\lambda \quad (32)$$

$$+ \begin{pmatrix} \sigma_\delta & 0 & 0 \\ \sigma_f \rho & \sigma_f \sqrt{1-\rho^2} & 0 \\ 0 & 0 & \sqrt{1-\phi^2} \end{pmatrix} \begin{pmatrix} dW_t^\delta \\ dW_t^f \\ dW_t^i \end{pmatrix}, \quad (33)$$

where  $i \in \{A, B\}$ . The unobservable process  $\lambda$  satisfies

$$d\lambda_t = (a_0 + a_1\lambda_t)dt + b_1dW_t^\lambda + b_2 \begin{pmatrix} dW_t^\delta \\ dW_t^f \\ dW_t^i \end{pmatrix} \quad (34)$$

$$= (\kappa\bar{\lambda} + (-\kappa)\lambda_t) dt + \Phi dW_t^\lambda + \begin{pmatrix} 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} dW_t^\delta \\ dW_t^f \\ dW_t^i \end{pmatrix}. \quad (35)$$

Therefore,

$$bob = b_1b'_1 + b_2b'_2 = \Phi^2 \quad (36)$$

$$BoB = B_1B'_1 + B_2B'_2 = \begin{pmatrix} \sigma_\delta^2 & \rho\sigma_f\sigma_\delta & 0 \\ \rho\sigma_f\sigma_\delta & \sigma_f^2 & 0 \\ 0 & 0 & 1 \end{pmatrix} \quad (37)$$

$$boB = b_1B'_1 + b_2B'_2 = \begin{pmatrix} 0 & 0 & \phi\Phi \end{pmatrix}. \quad (38)$$

The estimated process defined by  $\hat{\lambda}_t^i = \mathbb{E}^{\mathbb{P}^i}(\lambda_t | \mathcal{O}_t)$  has dynamics

$$d\hat{\lambda}_t^i = \left( a_0 + a_1\hat{\lambda}_t^i \right) dt + (boB + \gamma_t A'_1)(BoB)^{-1} \left[ \begin{pmatrix} d\zeta_t \\ df_t \\ ds_t^i \end{pmatrix} - \begin{pmatrix} A_0 + A_1\hat{\lambda}_t^i \end{pmatrix} dt \right], \quad (39)$$

where the uncertainty  $\gamma$  solves the following Ordinary Differential Equation

$$\frac{d\gamma_t}{dt} = a_1\gamma_t + \gamma_t a'_1 + bob - (boB + \gamma_t A'_1)(BoB)^{-1}(boB + \gamma_t A'_1)'. \quad (40)$$



Consequently,

$$d\widehat{\lambda}_t^i = \kappa \left( \bar{\lambda} - \widehat{\lambda}_t^i \right) dt + \left( 0 \quad \frac{(\bar{f} - f_t)\gamma_t}{\sigma_f \sqrt{1 - \rho^2}} \quad \phi \Phi \right) \begin{pmatrix} d\widehat{W}_t^\delta \\ d\widehat{W}_t^{fi} \\ d\widehat{W}_t^{si} \end{pmatrix}, \quad (41)$$

where the three Brownians are independent and are defined as follows:

$$d\widehat{W}_t^\delta = dW_t^\delta \quad (42)$$

$$d\widehat{W}_t^{fi} = \frac{1}{\sigma_f \sqrt{1 - \rho^2}} \left[ df_t - \widehat{\lambda}_t^i (\bar{f} - f_t) dt - \sigma_f \rho dW_t^\delta \right] \quad (43)$$

$$d\widehat{W}_t^{si} = ds_t^i \quad (44)$$

The dynamics of uncertainty are

$$\frac{d\gamma_t}{dt} = (1 - \phi^2) \Phi^2 - 2\kappa\gamma_t - \frac{(\bar{f} - f_t)^2}{\sigma_f^2 (1 - \rho^2)} \gamma_t^2. \quad (45)$$

The long-term uncertainty,  $\bar{\gamma}$ , solves  $\frac{d\gamma_t}{dt} \Big|_{f_t = \bar{f}} = 0$  and hence satisfies  $\bar{\gamma} = \frac{(1 - \phi^2)\Phi^2}{2\kappa}$ . As the dynamics (45) show,  $\bar{\gamma}$  represents an upper bound of uncertainty: when  $f_t = \bar{f}$  the last term in (45) vanishes and uncertainty converges to  $\bar{\gamma}$ . It is only when  $f_t \neq \bar{f}$  that uncertainty moves away (downwards) from this upper bound.

## A.2 Proof of Proposition 1

Consider the following 4-dimensional Brownian motion defined under the probability measure of agent  $B$ :

$$d\widehat{W} = \begin{pmatrix} \widehat{W}^\delta \\ \widehat{W}^{fB} \\ \widehat{W}^{sB} \\ \widehat{W}^{sA*} \end{pmatrix} \quad (46)$$

where the first three Brownians are defined in (42), (43) and (44). The last Brownian is defined such that (this ensures that the correlation between  $d\widehat{W}^{sA}$  and  $d\widehat{W}^{sB}$  is  $\phi^2$ ):

$$d\widehat{W}^{sA} = \phi^2 d\widehat{W}^{sB} + \sqrt{1 - \phi^4} d\widehat{W}^{sA*} \quad (47)$$

Write the dynamics of the vector of state variables under the probability measure of agent  $B$ :



$$d\zeta_t = \left( f_t - \frac{1}{2}\sigma_\delta^2 \right) dt + (\sigma_\delta \ 0 \ 0 \ 0) d\widehat{W}_t \quad (48)$$

$$df_t = \widehat{\lambda}_t^B (\bar{f} - f_t) dt + \left( \sigma_f \rho \ \sigma_f \sqrt{1 - \rho^2} \ 0 \ 0 \right) d\widehat{W}_t \quad (49)$$

$$d\widehat{\lambda}_t^A = \left( \kappa (\bar{\lambda} - \widehat{\lambda}_t^A) + \frac{\gamma_t (\widehat{\lambda}_t^B - \widehat{\lambda}_t^A)}{\sigma_f^2 (1 - \rho^2)} (\bar{f} - f_t)^2 \right) dt \quad (50)$$

$$+ \left( 0 \ \frac{\gamma_t}{\sigma_f \sqrt{1 - \rho^2}} (\bar{f} - f_t) \ \phi^3 \Phi \ \phi \Phi \sqrt{1 - \phi^4} \right) d\widehat{W}_t \quad (51)$$

$$d\widehat{\lambda}_t^B = \kappa (\bar{\lambda} - \widehat{\lambda}_t^B) dt + \left( 0 \ \frac{\gamma_t}{\sigma_f \sqrt{1 - \rho^2}} (\bar{f} - f_t) \ \phi \Phi \ 0 \right) d\widehat{W}_t \quad (52)$$

$$d\gamma_t = \left( (1 - \phi^2) \Phi - 2\kappa \gamma_t - \frac{(f_t - \bar{f})^2}{\sigma_f^2 (1 - \rho^2)} \gamma_t^2 \right) dt \quad (53)$$

$$d\mu_t = -\frac{1}{2} \frac{(\widehat{\lambda}_t^B - \widehat{\lambda}_t^A)^2 (\bar{f} - f_t)^2}{\sigma_f^2 (1 - \rho^2)} dt + \left( 0 \ -\frac{(\widehat{\lambda}_t^B - \widehat{\lambda}_t^A)(\bar{f} - f_t)}{\sigma_f \sqrt{1 - \rho^2}} \ 0 \ 0 \right) d\widehat{W}_t, \quad (54)$$

The dynamics of disagreement are given by:

$$d(\widehat{\lambda}_t^B - \widehat{\lambda}_t^A) = - \left( \kappa + \frac{\gamma_t (\bar{f} - f_t)^2}{\sigma_f^2 (1 - \rho^2)} \right) (\widehat{\lambda}_t^B - \widehat{\lambda}_t^A) dt + \left( 0 \ 0 \ \phi \Phi (1 - \phi^2) \ \phi \Phi \sqrt{1 - \phi^4} \right) d\widehat{W}_t, \quad (55)$$

and thus its conditional variance is

$$2\phi^2 \Phi^2 (1 - \phi^2). \quad (56)$$

The optimization problem of agent  $B$  is

$$\max_{c_{Bt}} \mathbb{E} \left[ \int_0^\infty e^{-\beta t} \frac{c_{Bt}^{1-\alpha}}{1-\alpha} dt \right] \quad (57)$$

$$\text{s.t. } \mathbb{E} \left[ \int_0^\infty \xi_t^B c_{Bt} dt \right] \leq x_{B0}, \quad (58)$$

where  $\xi^B$  denotes the state-price density perceived by agent  $B$  and  $x_{B0}$  is her initial wealth. Under the probability measure  $\mathbb{P}^B$ , the problem of agent  $A$  is

$$\max_{c_{At}} \mathbb{E} \left[ \int_0^\infty \eta_t e^{-\beta t} \frac{c_{At}^{1-\alpha}}{1-\alpha} dt \right] \quad (59)$$

$$\text{s.t. } \mathbb{E} \left[ \int_0^\infty \xi_t^B c_{At} dt \right] \leq x_{A0}. \quad (60)$$

Note that the change of measure enters directly the objective function of agent  $A$  but not its budget constraint (60). The reason is that the budget constraint depends on the state-price density



perceived by agent  $B$ .<sup>33</sup> The first-order conditions are

$$c_{Bt} = \left( \Lambda_B e^{\beta t} \xi_t^B \right)^{-\frac{1}{\alpha}} \quad (61)$$

$$c_{At} = \left( \frac{\Lambda_A}{\eta_t} e^{\beta t} \xi_t^B \right)^{-\frac{1}{\alpha}}, \quad (62)$$

where  $\Lambda_A$  and  $\Lambda_B$  are the Lagrange multipliers associated with the budget constraints of agents  $A$  and  $B$ , respectively. Summing up agents' optimal consumption policies and imposing market clearing, i.e.,  $c_{At} + c_{Bt} = \delta_t$ , yields the state-price density perceived by agent  $B$

$$\xi_t^B = e^{-\beta t} \delta_t^{-\alpha} \left[ \left( \frac{\eta_t}{\Lambda_A} \right)^{1/\alpha} + \left( \frac{1}{\Lambda_B} \right)^{1/\alpha} \right]^\alpha. \quad (63)$$

Substituting the state-price density  $\xi^B$  in the optimal consumption policies yields the following consumption sharing rules

$$c_{At} = \omega_{At} \delta_t \quad (64)$$

$$c_{Bt} = \omega_{Bt} \delta_t = (1 - \omega_{At}) \delta_t, \quad (65)$$

where  $\omega_{it}$  denotes agent  $i$ 's share of consumption at time  $t$  for  $i \in \{A, B\}$ . Agent  $A$ 's share of consumption satisfies

$$\omega_{At} = \frac{\left( \frac{\eta_t}{\Lambda_A} \right)^{1/\alpha}}{\left( \frac{\eta_t}{\Lambda_A} \right)^{1/\alpha} + \left( \frac{1}{\Lambda_B} \right)^{1/\alpha}}. \quad (66)$$

The evolution of agent  $B$ 's consumption share under her own probability measure follows

$$\frac{d\omega_{Bt}}{\omega_{Bt}} = \frac{1}{2} \frac{(1 - \omega_{Bt})(1 + \alpha - 2\omega_{Bt})}{\alpha^2 \sigma_f^2 (1 - \rho^2)} \mathcal{D}_t^2 dt + \frac{1 - \omega_{Bt}}{\alpha \sigma_f \sqrt{1 - \rho^2}} \mathcal{D}_t d\widehat{W}_t^{fB}. \quad (67)$$

Notice that the drift is always positive (as long as there is disagreement). This is also the case for the consumption share of agent  $A$ , under her own probability measure.

As in [Yan \(2008\)](#) and [Dumas et al. \(2009\)](#), we assume that the coefficient of relative risk aversion

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<sup>33</sup>Alternatively, we could have defined the state-price density perceived by agent  $A$ ,  $\xi^A$ . Then, we would have  $\mathbb{E}^A [\xi^A \mathbf{1}_x] = \mathbb{E}^B [\eta \xi^A \mathbf{1}_x] = \mathbb{E}^B [\xi^B \mathbf{1}_x]$  for any event  $x$ . That is,  $\xi^B = \eta \xi^A$ .



$\alpha$  is an integer. In this case, the state-price density at time  $u$  satisfies

$$\xi_u^B = e^{-\beta u} \delta_u^{-\alpha} \left[ \left( \frac{1}{\Lambda_B} \right)^{1/\alpha} + \left( \frac{\eta_u}{\Lambda_A} \right)^{1/\alpha} \right]^\alpha \quad (68)$$

$$= e^{-\beta u} \delta_u^{-\alpha} \frac{1}{\Lambda_B} \sum_{j=0}^{\alpha} \binom{\alpha}{j} \left( \frac{\eta_u \Lambda_B}{\Lambda_A} \right)^{\frac{j}{\alpha}} \quad (69)$$

$$= e^{-\beta u} \delta_u^{-\alpha} \frac{1}{\Lambda_B} \sum_{j=0}^{\alpha} \binom{\alpha}{j} \left( \frac{1}{\eta_t} \right)^{\frac{j}{\alpha}} \left( \frac{\eta_t \Lambda_B}{\Lambda_A} \right)^{\frac{j}{\alpha}} \eta_u^{\frac{j}{\alpha}} \quad (70)$$

$$= e^{-\beta u} \delta_u^{-\alpha} \frac{1}{\Lambda_B} \sum_{j=0}^{\alpha} \binom{\alpha}{j} \left( \frac{\eta_u}{\eta_t} \right)^{\frac{j}{\alpha}} \left( \frac{\omega_{At}}{1 - \omega_{At}} \right)^j, \quad (71)$$

where the last equality comes from the fact that

$$\omega_{At} = \frac{\left( \frac{\eta_t}{\Lambda_A} \right)^{1/\alpha}}{\left( \frac{1}{\Lambda_B} \right)^{1/\alpha} + \left( \frac{\eta_t}{\Lambda_A} \right)^{1/\alpha}} \quad (72)$$

$$1 - \omega_{At} = \frac{\left( \frac{1}{\Lambda_B} \right)^{1/\alpha}}{\left( \frac{1}{\Lambda_B} \right)^{1/\alpha} + \left( \frac{\eta_t}{\Lambda_A} \right)^{1/\alpha}}, \quad (73)$$

and consequently

$$\left( \frac{\eta_t \Lambda_B}{\Lambda_A} \right)^{\frac{1}{\alpha}} = \frac{\omega_{At}}{1 - \omega_{At}}. \quad (74)$$

Rewriting Equation (73) yields

$$\left( \frac{1}{\Lambda_B} \right)^{1/\alpha} + \left( \frac{\eta_t}{\Lambda_A} \right)^{1/\alpha} = \left( \frac{1}{1 - \omega_{At}} \right) \left( \frac{1}{\Lambda_B} \right)^{\frac{1}{\alpha}}, \quad (75)$$

and thus

$$\xi_t^B = e^{-\beta t} \delta_t^{-\alpha} \left( \frac{1}{1 - \omega_{At}} \right)^\alpha \frac{1}{\Lambda_B} = \frac{1}{\Lambda_B} e^{-\beta t} (\delta_t \omega_{Bt})^{-\alpha}, \quad (76)$$



which is Equation (20) in the text. Thus, the dynamics for the stochastic discount follow:

$$\frac{d\xi_t}{\xi_t} = - \left[ \beta + \alpha f_t - \frac{1}{2} \alpha (\alpha + 1) \sigma_\delta^2 \right. \quad (77)$$

$$\left. + \alpha \frac{1}{2} \frac{(1 - \omega_{Bt})(1 + \alpha - 2\omega_{Bt})}{\alpha^2 \sigma_f^2 (1 - \rho^2)} \mathcal{D}_t^2 - \frac{1}{2} \alpha (\alpha + 1) \frac{(1 - \omega_{Bt})^2}{\alpha^2 \sigma_f^2 (1 - \rho^2)} \mathcal{D}_t^2 \right] dt \quad (78)$$

$$- \underbrace{\left( \alpha \sigma_\delta \quad \frac{\mathcal{D}_t}{\sigma_f \sqrt{1 - \rho^2}} \omega_{At} \quad 0 \quad 0 \right)}_{\text{Market price of risk}} \begin{pmatrix} d\widehat{W}_t^\delta \\ d\widehat{W}_t^{fB} \\ d\widehat{W}_t^{sB} \\ d\widehat{W}_t^{sA*} \end{pmatrix}, \quad (79)$$

and the risk-free rate is given by

$$r_t = \beta + \alpha f_t - \frac{1}{2} \alpha (\alpha + 1) \sigma_\delta^2 + \frac{1}{2} \frac{\alpha - 1}{\alpha} \frac{\mathcal{D}_t^2}{\sigma_f^2 (1 - \rho^2)} \omega_{At} \omega_{Bt}. \quad (80)$$

The price-dividend ratio satisfies

$$\frac{S_t}{\delta_t} = \mathbb{E}_t \left( \int_t^\infty \frac{\xi_u^B}{\xi_t^B} \frac{\delta_u}{\delta_t} du \right) \quad (81)$$

$$\stackrel{(71) (75) (76)}{=} \mathbb{E}_t \left( \int_t^\infty \frac{e^{-\beta u} \delta_u^{-\alpha} \frac{1}{\Lambda_B} \sum_{j=0}^\alpha \binom{\alpha}{j} \left( \frac{\eta_u}{\eta_t} \right)^{\frac{j}{\alpha}} \left( \frac{\omega_{At}}{1 - \omega_{At}} \right)^j}{e^{-\beta t} \left( \frac{1}{1 - \omega_{At}} \right)^\alpha \frac{1}{\Lambda_B} \delta_t^{-\alpha}} \frac{\delta_u}{\delta_t} du \right) \quad (82)$$

$$= \mathbb{E}_t \left( \int_t^\infty e^{-\beta(u-t)} \frac{\sum_{j=0}^\alpha \binom{\alpha}{j} \left( \frac{\eta_u}{\eta_t} \right)^{\frac{j}{\alpha}} \left( \frac{\omega_{At}}{1 - \omega_{At}} \right)^j}{\left( \frac{1}{1 - \omega_{At}} \right)^\alpha} \left( \frac{\delta_u}{\delta_t} \right)^{1-\alpha} du \right) \quad (83)$$

$$= \sum_{j=0}^\alpha \binom{\alpha}{j} \omega_{At}^j (1 - \omega_{At})^{\alpha-j} \mathbb{E}_t \left( \int_t^\infty e^{-\beta(u-t)} \left( \frac{\eta_u}{\eta_t} \right)^{\frac{j}{\alpha}} \left( \frac{\delta_u}{\delta_t} \right)^{1-\alpha} du \right). \quad (84)$$

Let us define the function  $F_j(Z)$  as follows

$$F_j(Z_t) \equiv \mathbb{E}_t \left[ \int_t^\infty e^{-\beta(u-t)} \left( \frac{\eta_u}{\eta_t} \right)^\epsilon \left( \frac{\delta_u}{\delta_t} \right)^\chi du \right], \quad (85)$$

where  $\epsilon = \frac{j}{\alpha}$ ,  $j = 0, \dots, \alpha$ ,  $\chi = 1 - \alpha$ , and  $Z \equiv \left( f, \widehat{\lambda}^A, \widehat{\lambda}^B, \gamma \right)^\top$  is a vector of state-variables that does not comprise  $\zeta = \log \delta$  and  $\mu = \log \eta$ .

Using these notations, the price-dividend ratio satisfies

$$\frac{S_t}{\delta_t} = \sum_{j=0}^\alpha \binom{\alpha}{j} \omega_{At}^j (1 - \omega_{At})^{\alpha-j} F_j(Z_t) \quad (86)$$

$$= \sum_{j=0}^\alpha \binom{\alpha}{j} \omega_{At}^j \omega_{Bt}^{\alpha-j} F_j(Z_t), \quad (87)$$

which is Equation (23) in Proposition 1.



### A.3 Solution method (Chebyshev Collocation)

We have

$$\left(\frac{\eta_u}{\eta_t}\right)^\epsilon = e^{-\frac{1}{2} \int_t^u \epsilon \left( \frac{(\hat{\lambda}_s^B - \hat{\lambda}_s^A)(\bar{f} - f_s)}{\sigma_f \sqrt{1-\rho^2}} \right)^2 ds - \int_t^u \begin{pmatrix} 0 & \epsilon \left( \frac{(\hat{\lambda}_s^B - \hat{\lambda}_s^A)(\bar{f} - f_s)}{\sigma_f \sqrt{1-\rho^2}} \right) & 0 & 0 \end{pmatrix} d\widehat{W}_t} \quad (88)$$

$$\left(\frac{\delta_u}{\delta_t}\right)^\chi = e^{\int_t^u \chi(f_s - \frac{1}{2}\sigma_\delta^2) ds + \int_t^u \begin{pmatrix} \chi\sigma_\delta & 0 & 0 & 0 \end{pmatrix} d\widehat{W}_t}, \quad (89)$$

where  $\epsilon$  and  $\chi$  are some constants. Therefore,

$$\left(\frac{\eta_u}{\eta_t}\right)^\epsilon \left(\frac{\delta_u}{\delta_t}\right)^\chi = e^{\int_t^u \left[ \chi(f_s - \frac{1}{2}\sigma_\delta^2) - \frac{1}{2}\epsilon \left( \frac{(\hat{\lambda}_s^B - \hat{\lambda}_s^A)(\bar{f} - f_s)}{\sigma_f \sqrt{1-\rho^2}} \right)^2 + \frac{1}{2} \left( \chi^2 \sigma_\delta^2 + \epsilon^2 \left( \frac{(\hat{\lambda}_s^B - \hat{\lambda}_s^A)(\bar{f} - f_s)}{\sigma_f \sqrt{1-\rho^2}} \right)^2 \right) \right] ds} \quad (90)$$

$$\times e^{-\frac{1}{2} \int_t^u \left( \chi^2 \sigma_\delta^2 + \epsilon^2 \left( \frac{(\hat{\lambda}_s^B - \hat{\lambda}_s^A)(\bar{f} - f_s)}{\sigma_f \sqrt{1-\rho^2}} \right)^2 \right) ds - \int_t^u \begin{pmatrix} -\chi\sigma_\delta & \epsilon \left( \frac{(\hat{\lambda}_s^B - \hat{\lambda}_s^A)(\bar{f} - f_s)}{\sigma_f \sqrt{1-\rho^2}} \right) & 0 & 0 \end{pmatrix} d\widehat{W}_t} \quad (91)$$

Note that last term of the first row cancels the first term of the second row. Importantly, the second row defines a change of measure. The change of measure is

$$\left. \frac{d\bar{\mathbb{P}}}{d\mathbb{P}^B} \right|_{\mathcal{O}_t} \equiv \nu_t = e^{-\frac{1}{2} \int_t^u \left( \chi^2 \sigma_\delta^2 + \epsilon^2 \left( \frac{(\hat{\lambda}_s^B - \hat{\lambda}_s^A)(\bar{f} - f_s)}{\sigma_f \sqrt{1-\rho^2}} \right)^2 \right) ds - \int_t^u \begin{pmatrix} -\chi\sigma_\delta & \epsilon \left( \frac{(\hat{\lambda}_s^B - \hat{\lambda}_s^A)(\bar{f} - f_s)}{\sigma_f \sqrt{1-\rho^2}} \right) & 0 & 0 \end{pmatrix} d\widehat{W}_t}, \quad (92)$$

where the  $\bar{\mathbb{P}}$ -Brownian motion  $\bar{W}$  is defined as

$$d\bar{W}_t = d\widehat{W}_t + y_t dt \quad (93)$$

$$y_t = \begin{pmatrix} -\chi\sigma_\delta & \epsilon \left( \frac{(\hat{\lambda}_t^B - \hat{\lambda}_t^A)(\bar{f} - f_t)}{\sigma_f \sqrt{1-\rho^2}} \right) & 0 & 0 \end{pmatrix}^\top. \quad (94)$$

Rewriting the problem under the probability measure  $\bar{\mathbb{P}}$  yields

$$F(Z_t) \equiv \bar{\mathbb{E}}_t \left[ \int_t^\infty e^{\int_t^u X_s ds} du \right], \quad (95)$$

where  $X_t = -\beta + \frac{1}{2} \frac{(\hat{\lambda}_t^B - \hat{\lambda}_t^A)^2 (\bar{f} - f_t)^2}{\sigma_f^2 (1-\rho^2)} (\epsilon^2 - \epsilon) + \chi(f_t - \frac{1}{2}\sigma_\delta^2) + \frac{1}{2}\chi^2\sigma_\delta^2$ . For notational ease, we drop the index  $j$  when defining the function  $F(\cdot)$  by keeping in mind that  $\epsilon = \frac{j}{\alpha}$  and  $\chi = 1 - \alpha$  in our setup. We now transform this expression to obtain a  $\bar{\mathbb{P}}$ -martingale. We have

$$F(Z_t) e^{\int_0^t X_s ds} + \int_0^t e^{\int_0^u X_s ds} du = \bar{\mathbb{E}}_t \left[ \int_0^\infty e^{\int_0^u X_s ds} du \right] \equiv \bar{M}_t, \quad (96)$$

where  $\bar{M}$  is a  $\bar{\mathbb{P}}$ -martingale. Applying Itô's lemma to the martingale  $\bar{M}$  and setting its drift to zero yields the following Partial Differential Equation for the function  $F(Z)$

$$\mathcal{L}^Z F(Z) + F(Z)X(Z) + 1 = 0, \quad (97)$$



where  $\mathcal{L}^Z$  is the  $\bar{\mathbb{P}}$ -infinitesimal generator with respect to the vector of state variables  $Z \equiv (f, \hat{\lambda}^A, \hat{\lambda}^B, \gamma)^\top$ .

PDE (97) is solved numerically using the Chebyshev collocation method (Judd, 1998). This method consists in approximating the function  $F(Z)$  as follows:

$$F(Z) \approx P(Z) = \sum_{i=0}^I \sum_{j=0}^J \sum_{k=0}^K \sum_{l=0}^L a_{i,j,k,l} T_i(f) T_j(\hat{\lambda}^A) T_k(\hat{\lambda}^B) T_l(\gamma),$$

where  $T_m$  is the Chebyshev polynomial of order  $m$ . We mesh the roots of the Chebyshev polynomials of order  $I + 1$ ,  $J + 1$ ,  $K + 1$ , and  $L + 1$  to obtain the interpolation nodes. Furthermore, these interpolation nodes are such that they cover the 99% confidence interval of each state variable. Substituting  $P(Z)$  and its partial derivatives in the PDE and evaluating the latter at the interpolation nodes yields a system of  $(I + 1) \times (J + 1) \times (K + 1) \times (L + 1)$  equations with  $(I + 1) \times (J + 1) \times (K + 1) \times (L + 1)$  unknowns (the coefficients  $a_{i,j,k,l}$ ). This system is solved numerically by minimizing the sum of squared PDE residuals at the interpolation nodes.

This method is very accurate even when the order of the Chebyshev polynomials is relatively low. Indeed, choosing  $I = J = K = L = 4$  yields  $5^4 = 625$  interpolation nodes. In our setup, the sum (over these 625 interpolation nodes) of squared PDE residuals is of order  $10^{-33}$  only. Furthermore, simulations show that the orders of the 1-percentile, median, and 99-percentile of squared residuals are  $10^{-19}$ ,  $10^{-15}$ , and  $10^{-12}$ , respectively. This provides evidence that the method is accurate.

## A.4 Calibration to the U.S. economy (Maximum Likelihood)

The log dividend growth rate and the fundamental are discretized as follows:

$$\log(\delta_{t+\Delta}/\delta_t) \approx \left(f_t - \frac{1}{2}\sigma_\delta^2\right)\Delta + \sigma_\delta\sqrt{\Delta}\epsilon_{1,t+\Delta} \quad (98)$$

$$f_{t+\Delta} \approx e^{-\hat{\lambda}_t^B \Delta} f_t + \bar{f} \left(1 - e^{-\hat{\lambda}_t^B \Delta}\right) + \frac{\sigma_f \rho}{\sqrt{2\hat{\lambda}_t^B}} \left(1 - e^{-2\hat{\lambda}_t^B \Delta}\right) \epsilon_{1,t+\Delta} \quad (99)$$

$$+ \frac{\sigma_f \sqrt{1-\rho^2}}{\sqrt{2\hat{\lambda}_t^B}} \left(1 - e^{-2\hat{\lambda}_t^B \Delta}\right) \epsilon_{2,t+\Delta}, \quad (100)$$

where  $\epsilon_1, \epsilon_2 \sim N(0, 1)$  are i.i.d and  $\Delta = 1/4$  because our dataset is at quarterly frequency. We fit  $\log(\delta_{t+\Delta}/\delta_t)$  and  $f_t$  to the realized real GDP growth over the current quarter and median real GDP growth forecast for the current quarter, respectively.

In the same spirit, Agent  $A$ 's forecast at horizon  $s - t$ ,  $f_{t,s-t}^A$ , and Agent  $B$ 's forecast at horizon  $s - t$ ,  $f_{t,s-t}^B$ , are discretized as follows:

$$f_{t,s-t}^A = E_t^A(f_s) \approx e^{-\hat{\lambda}_t^A(s-t)} f_t + \bar{f} \left(1 - e^{-\hat{\lambda}_t^A(s-t)}\right) \quad (101)$$

$$f_{t,s-t}^B = E_t^B(f_s) \approx e^{-\hat{\lambda}_t^B(s-t)} f_t + \bar{f} \left(1 - e^{-\hat{\lambda}_t^B(s-t)}\right). \quad (102)$$

Applying Itô's lemma to Equations (101) and (102), substituting  $f_t$  by its value extracted from Equations (101) and (102), and setting  $s - t = \Delta = 1/4$  yields the following dynamics for the



1-quarter-ahead forecasts computed by Agent  $A$ ,  $f_{t,\Delta}^A$ , and Agent  $B$ ,  $f_{t,\Delta}^B$

$$df_{t,\Delta}^A = a_1(f_{t,\Delta}^A, \hat{\lambda}_t^A, \hat{\lambda}_t^B, \gamma_t)dt + b_1(f_{t,\Delta}^A, \hat{\lambda}_t^A, \gamma_t)d\widehat{W}_t, \quad (103)$$

$$df_{t,\Delta}^B = a_2(f_{t,\Delta}^B, \hat{\lambda}_t^B, \gamma_t)dt + b_2(f_{t,\Delta}^B, \hat{\lambda}_t^B, \gamma_t)d\widehat{W}_t, \quad (104)$$

where the drifts  $a_1(\cdot), a_2(\cdot) \in \mathbb{R}$  and the diffusions  $b_1(\cdot), b_2(\cdot) \in \mathbb{R}^4$  satisfy

$$a_1(f_{t,\Delta}^A, \hat{\lambda}_t^A, \hat{\lambda}_t^B, \gamma_t) = \frac{1}{2(1-\rho^2)\sigma_f^2}(\bar{f} - f_{t,\Delta}^A) \left( e^{2\Delta\hat{\lambda}_t^A} \Delta(\bar{f} - f_{t,\Delta}^A)^2 \gamma_t (\Delta\gamma_t + 2(\hat{\lambda}_t^A - \hat{\lambda}_t^B)) \right. \quad (105)$$

$$\left. -(-1 + \rho^2)\sigma_f^2(\Delta(-2\kappa\bar{\lambda} + \Delta\phi^2\Phi^2) + 2\hat{\lambda}_t^A + 2\Delta(\gamma_t + \kappa\hat{\lambda}_t^A) - 2\hat{\lambda}_t^B) \right), \quad (106)$$

$$a_2(f_{t,\Delta}^B, \hat{\lambda}_t^B, \gamma_t) = \frac{1}{2}\Delta(\bar{f} - f_{t,\Delta}^B) \left( 2\kappa\bar{\lambda} - \Delta\phi^2\Phi^2 + \gamma_t \left( -2 + \frac{e^{2\Delta\hat{\lambda}_t^B} \Delta(\bar{f} - f_{t,\Delta}^B)^2 \gamma_t}{(-1 + \rho^2)\sigma_f^2} \right) - 2\kappa\hat{\lambda}_t^B \right), \quad (107)$$

$$b_1(f_{t,\Delta}^A, \hat{\lambda}_t^A, \gamma_t) = \begin{pmatrix} \frac{e^{-\Delta\hat{\lambda}_t^A} \rho \sigma_f}{e^{\Delta\hat{\lambda}_t^A} (-e^{-2\Delta\hat{\lambda}_t^A} (-1 + \rho^2)\sigma_f^2 + \Delta(\bar{f} - f_{t,\Delta}^A)^2 \gamma_t)} \\ \frac{\sqrt{1-\rho^2}\sigma_f}{\Delta\phi^3\Phi(\bar{f} - f_{t,\Delta}^A)} \\ \frac{\Delta\phi\sqrt{1-\phi^4}\Phi(\bar{f} - f_{t,\Delta}^A)}{\Delta\phi\sqrt{1-\phi^4}\Phi(\bar{f} - f_{t,\Delta}^A)} \end{pmatrix}^\top, \quad (108)$$

$$b_2(f_{t,\Delta}^B, \hat{\lambda}_t^B, \gamma_t) = \begin{pmatrix} \frac{e^{-\Delta\hat{\lambda}_t^B} \rho \sigma_f}{e^{\Delta\hat{\lambda}_t^B} (-e^{-2\Delta\hat{\lambda}_t^B} (-1 + \rho^2)\sigma_f^2 + \Delta(\bar{f} - f_{t,\Delta}^B)^2 \gamma_t)} \\ \frac{\sqrt{1-\rho^2}\sigma_f}{\Delta\phi\Phi(\bar{f} - f_{t,\Delta}^B)} \\ 0 \end{pmatrix}^\top. \quad (109)$$

Discretizing the dynamics in (103) and (104) yields

$$f_{t+\Delta,\Delta}^A = f_{t,\Delta}^A + a_1(f_{t,\Delta}^A, \hat{\lambda}_t^A, \hat{\lambda}_t^B, \gamma_t)\Delta + b_1(f_{t,\Delta}^A, \hat{\lambda}_t^A, \gamma_t)\sqrt{\Delta} \begin{pmatrix} \epsilon_{1,t+\Delta} \\ \epsilon_{2,t+\Delta} \\ \epsilon_{3,t+\Delta} \\ \epsilon_{4,t+\Delta} \end{pmatrix}, \quad (110)$$

$$f_{t+\Delta,\Delta}^B = f_{t,\Delta}^B + a_2(f_{t,\Delta}^B, \hat{\lambda}_t^B, \gamma_t)\Delta + b_2(f_{t,\Delta}^B, \hat{\lambda}_t^B, \gamma_t)\sqrt{\Delta} \begin{pmatrix} \epsilon_{1,t+\Delta} \\ \epsilon_{2,t+\Delta} \\ \epsilon_{3,t+\Delta} \\ \epsilon_{4,t+\Delta} \end{pmatrix} \quad (111)$$

where  $\epsilon_1, \epsilon_2, \epsilon_3, \epsilon_4 \sim N(0, 1)$  are i.i.d. Since we consider a 2-agent model, the lowest perceived value corresponds by definition to the 25th percentile and the highest value to the 75th percentile. Therefore, we fit  $f_{t,\Delta}^A$  and  $f_{t,\Delta}^B$  to the 75th percentile of the 1-quarter-ahead real GDP growth forecast and to the 25th percentile of the 1-quarter-ahead real GDP growth forecast, respectively. That is, agent  $B$  is the pessimistic agent and agent  $A$  the optimistic one. This assumption is motivated further in Appendix A.5.

The four time series, namely realized GDP growth, median of the current quarter GDP growth forecast, 75th percentile of the 1-quarter-ahead GDP growth forecast, and 25th percentile of the 1-quarter-ahead GDP growth forecast, are available at quarterly frequency from Q4:1968 to Q2:2016 and are obtained from the Federal Reserve Bank of Philadelphia's website.



Maximizing the log likelihood function implied by (98), (100), (110), and (111) yields the parameters and standard errors reported in Table 1. The estimation also provides the historical model-implied time series of the mean-reversion speed of agent  $A$ ,  $\hat{\lambda}^{A,e}$ , the mean-reversion speed of agent  $B$ ,  $\hat{\lambda}^{B,e}$ , and the uncertainty,  $\gamma^e$ . The historical time series of the fundamental consists of the median of the current quarter GDP growth forecast and is denoted by  $f^e \equiv f$ .

## A.5 Historical time series of the state variables

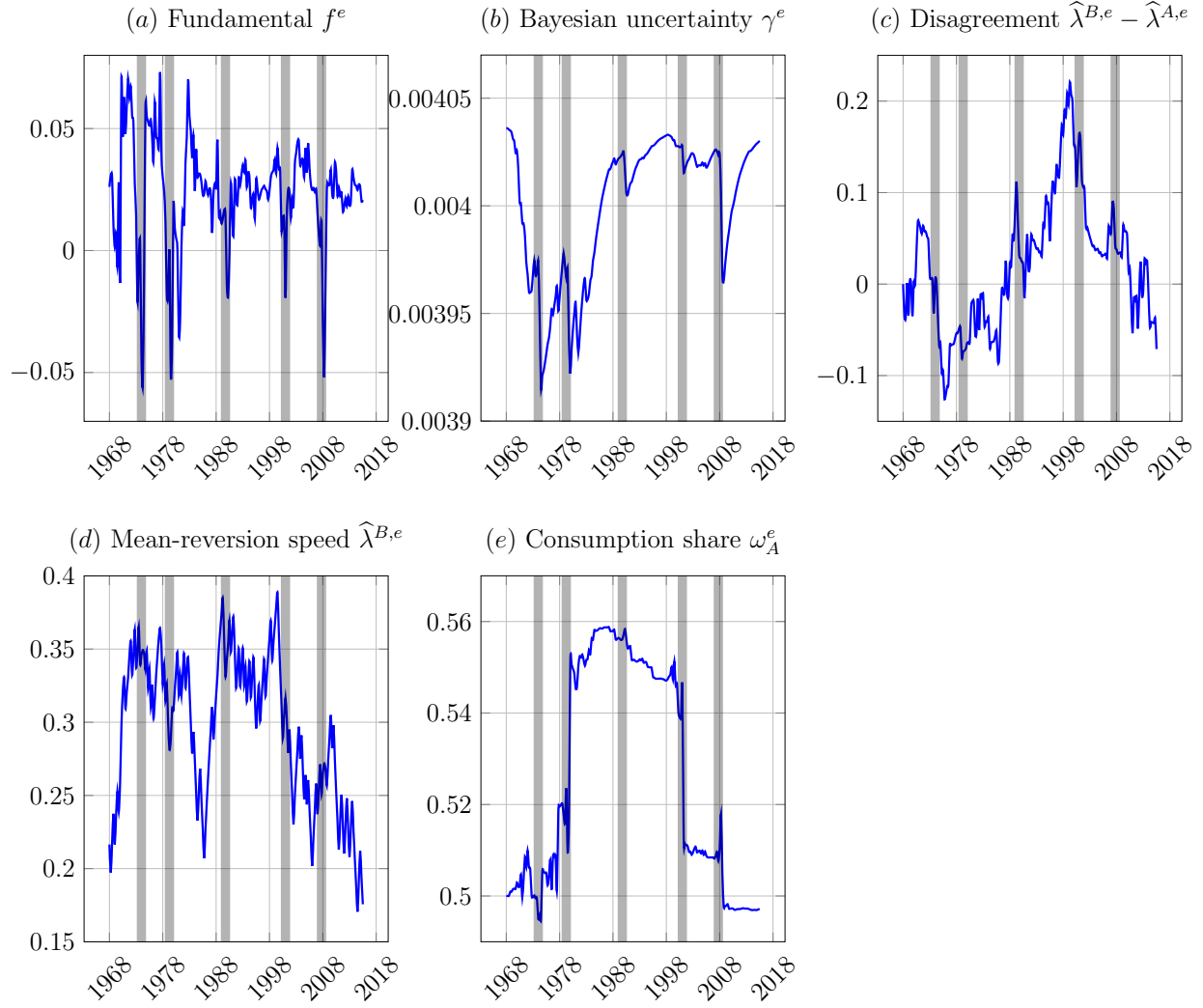
Figure 8 depicts the path of the state variables of the model from Q4:1968 to Q2:2016. These time series are recovered from the maximum likelihood estimation performed in Section 3.1. Unsurprisingly, panel (a) shows that the fundamental is particularly low during the NBER recessions of 1973-1975, 1980-1982, 1990-1991, 2001, and 2007-2009 (gray shaded areas). During these bad economic episodes, disagreement about the mean-reversion speed of the fundamental, and therefore about when the recovery will take place, was particularly high. Indeed, the (absolute) difference between the mean-reversion speeds is around 0.1 during these recessions, and even spikes to 0.2 before and during the recession of 2001.

Furthermore, agent  $A$ 's consumption share incurs large drops after the recessions of 2001 and 2007-2009, and ends up below 0.5 at the end of the sample. In other words, agent  $B$  slightly dominates agent  $A$  in terms of consumption share, which means that agent  $B$ 's beliefs are more realistic than agent  $A$ 's. This result motivates our assumption to fit agent  $B$ 's belief (which coincide with the correct/true belief in our model) to the 25th percentile of the 1-quarter-ahead analyst forecast and not to the 75th percentile. If we instead had assumed that agent  $B$  were the optimistic agent, then the agent with the correct beliefs (still agent  $B$ ) would have counterfactually ended up with a lower share of consumption.

## A.6 Model-simulated path of volatility and the state variables

Figure 9 plots one model-simulated path of stock return volatility and the corresponding state variables. Comparing panels (c) and (f) shows that, in our model, persistence in volatility is principally generated by persistence in Bayesian uncertainty.



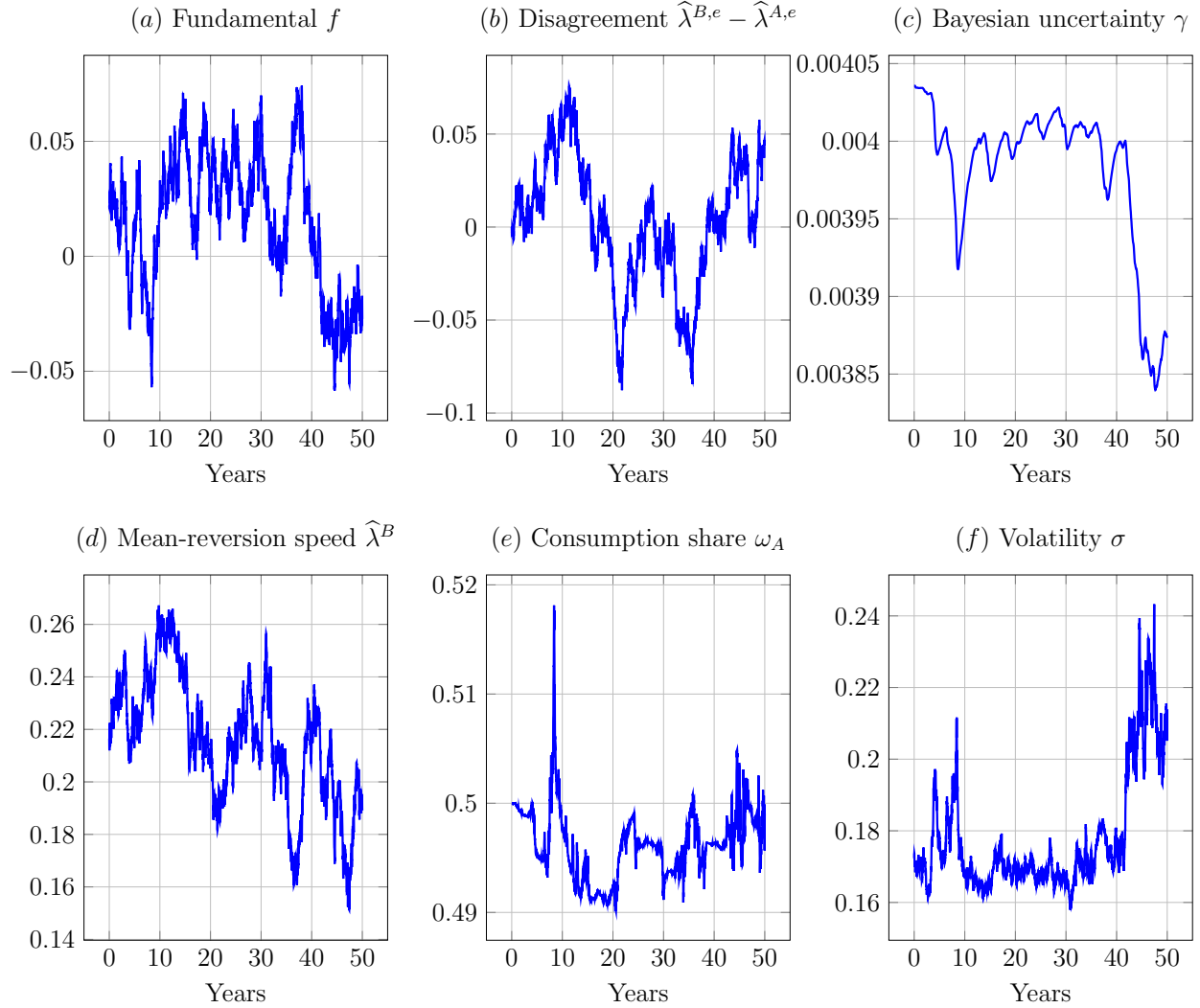


**Figure 8: Historical path of the state variables of the model**

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**Figure 9: Model-simulated path of volatility and the state variables**

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